

## EXTENSION PACK FOR GAMMA PLATFORM

2025.1



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## WHAT IS NEEDED?

Please make sure the PC where you want this module to be active have VAST.Rehab Patient Panel installed and that the following hardware requirements are met:

- Windows 10/11
- Intel Core i5 (8th gen or newer). Important: Avoid ultra-low-power versions (e.g., i5-8250U), as they may not meet performance requirements. Prefer standard or high-performance CPUs.
- Minimum: 8 GB RAM (16 GB or more recommended for optimal performance).





# SPEED RABBIT

Measure number of repetitions of specific movement pattern an individual is able to perform within predefined time interval.

### **CONTROL MODES**



### **RESULTS**



### **ADJUSTMENTS**

- Task duration
- Height of jump

### **OBJECTIVES**

- Speed of movement
- Repetitive movements

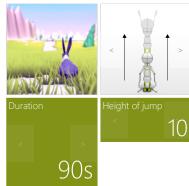
### **INSTRUCTION FOR PATIENT**

Go through the entire route as fast as you can.









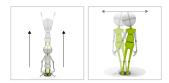




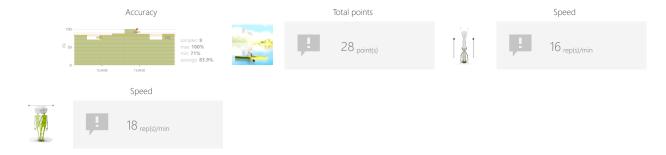
## SPEED KAYAK

Measure number of repetitions of specific movement pattern an individual is able to perform within predefined time interval.

### **CONTROL MODES**



## RESULTS



### **ADJUSTMENTS**

- Task duration
- Height of jump

### **OBJECTIVES**

- Speed of movement
- Repetitive movements

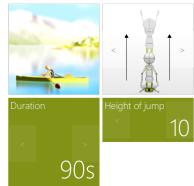
### **INSTRUCTION FOR PATIENT**

Row as fast as you can.













## BALANCE BLOCK BUILDER

Measure and train individual's skills to perform specific movement patterns while keeping predefined weight distribution.

### **CONTROL MODES**



### **RESULTS**



### **ADJUSTMENTS**

- Task duration
- Height of jump
- Stack height

### **OBJECTIVES**

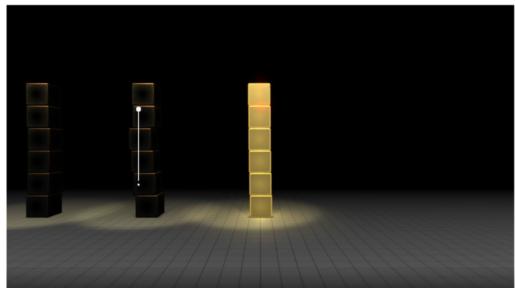
- Movement precision
- Muscle strengthening

### **INSTRUCTION FOR PATIENT**

Build as many stacks as you can. Keep your body balanced.











## MOVEMENT PRECISION

UMBRELLA

Measure and train individual's skills to perform specific movement patterns with predefined speed and range.

### **CONTROL MODES**



### **RESULTS**



### **ADJUSTMENTS**

- Task duration
- Path
- Range
- Umbrella size

### **OBJECTIVES**

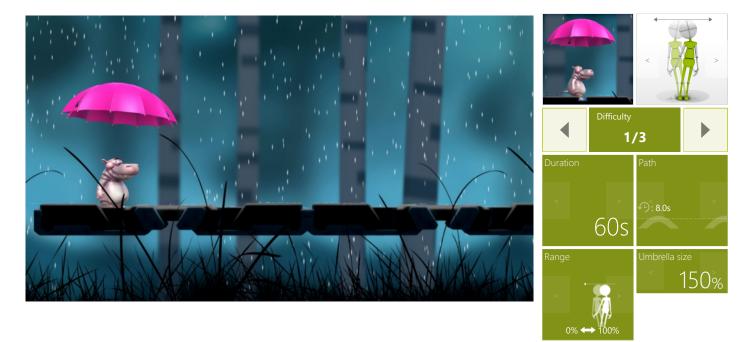
- Movement precision
- Visual motor coordination

### **INSTRUCTION FOR PATIENT**

Don't let the hippo get wet - keep the umbrella above him!









### **DRAGON**

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

### **CONTROL MODES**



### **RESULTS**



### **ADJUSTMENTS**

- Task duration
- Coins group size
- Height of jump
- Distance between coins
- Gravity force

### **OBJECTIVES**

- Predicting the trajectory of objects
- Improve range of motion
- Visual motor coordination
- Muscle strengthening
- Planning and Strategy

### INSTRUCTION FOR PATIENT

Fly and collect the coins.









### **RAILS**

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

### **CONTROL MODES**



### **RESULTS**



### **ADJUSTMENTS**

- Speed
- Task duration
- Range
- Route shape
- Enable derailing
- Enable obstacles
- Time between objects

### **OBJECTIVES**

- Dynamic responses to emerging moving targets
- Predicting the trajectory of objects
- Visual motor coordination

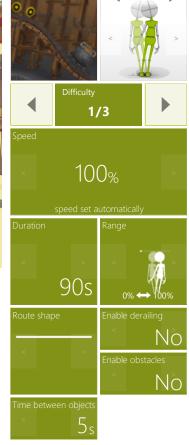
### INSTRUCTION FOR PATIENT

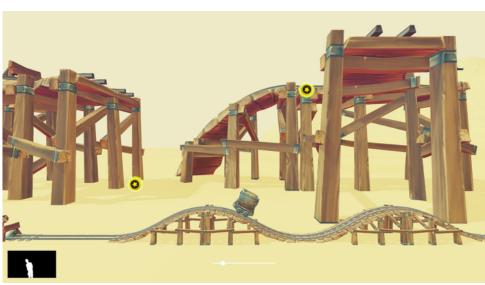
Control the trolley to collect the coins.

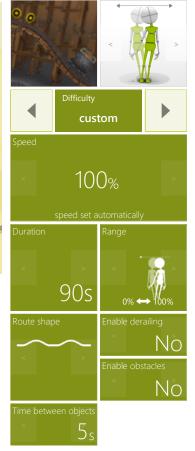
















### **MOTOCROSS**

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

### **CONTROL MODES**



### **RESULTS**



### **ADJUSTMENTS**

- Task duration
- Range
- Route shape

### **OBJECTIVES**

- Dynamics of planned movements
- Planning and Strategy

### INSTRUCTION FOR PATIENT

Accelerate and brake to cover the entire route as quickly as possible without tipping.









### **FOREST RUNNER**

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

### **CONTROL MODES**



### **RESULTS**



### **ADJUSTMENTS**

- Speed
- Task duration
- Range

### **OBJECTIVES**

- Dynamics of planned movements
- Focusing
- Planned movements
- Speed of movement

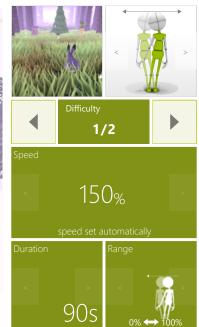
### INSTRUCTION FOR PATIENT

Keep the hare on the run, avoid obstacles and collect as many carrots as you can.











### DANCEMAN

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

### **CONTROL MODES**



### **RESULTS**



### **ADJUSTMENTS**

- Task duration
- Range
- Advanced scoring
- Song index
- Spawn rate level

### **OBJECTIVES**

- · Activity in a given rhythm
- Spontaneous movements
- Visual motor coordination

### INSTRUCTION FOR PATIENT

Hit the green characters when they come close.





