

VR BASE PACK

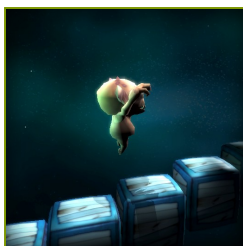
2025.1

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WHAT IS NEEDED?

Please make sure the PC where you want this module to be active have VAST.Rehab Patient Panel installed and that the following hardware requirements are met:

- Oculus Quest 2
- Oculus Quest 3

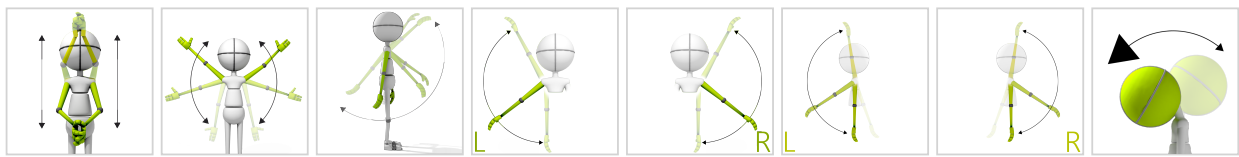


SPEED

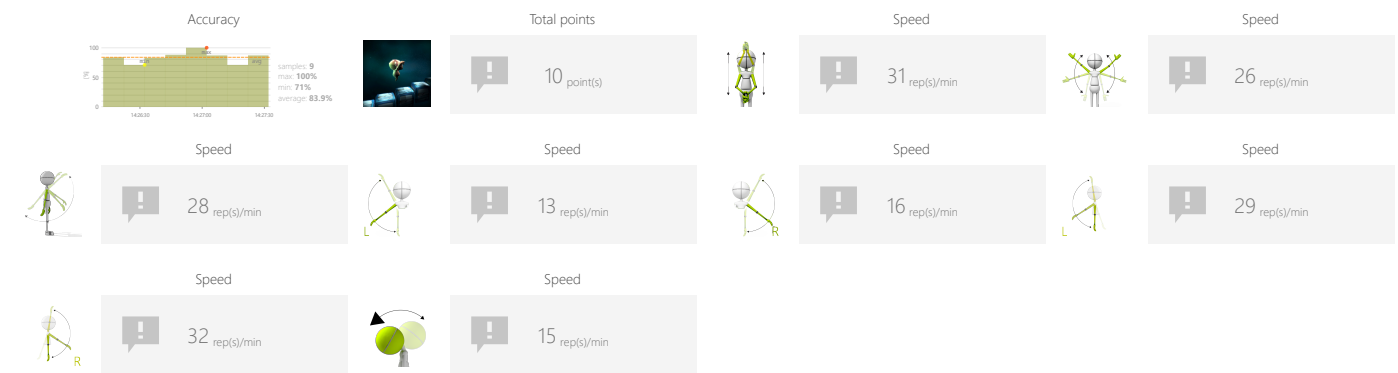
STAIRS

Measure number of repetitions of specific movement pattern an individual is able to perform within predefined time interval.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Max time per floor
- Number of stairs
- Pause length

OBJECTIVES

- Jumping
- Knees lifting
- Dynamics of planned movements

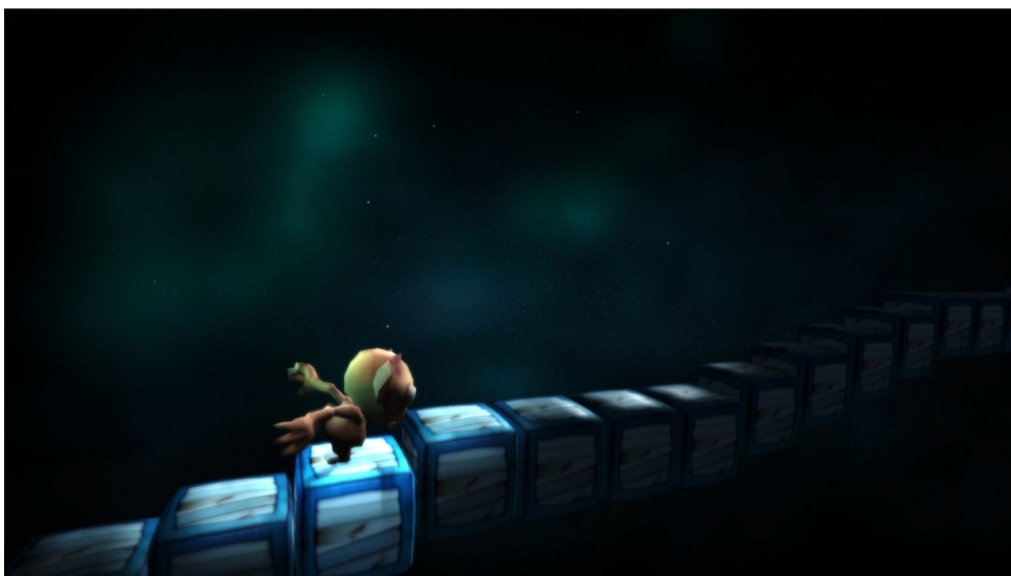
INSTRUCTION FOR PATIENT

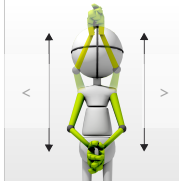
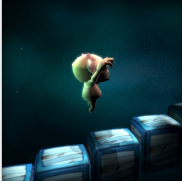
Climb the stairs before they disappear.



SPEED STAIRS

SAMPLE SETTINGS





◀


Difficulty
custom

▶

Duration

< 90s >

Range

20% 80% 

Max time per floor

< 15s >

Number of stairs

< 5 >

Pause length

< 3 >

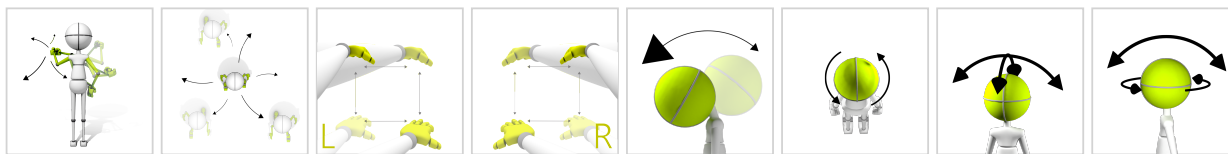


MOVEMENT PRECISION

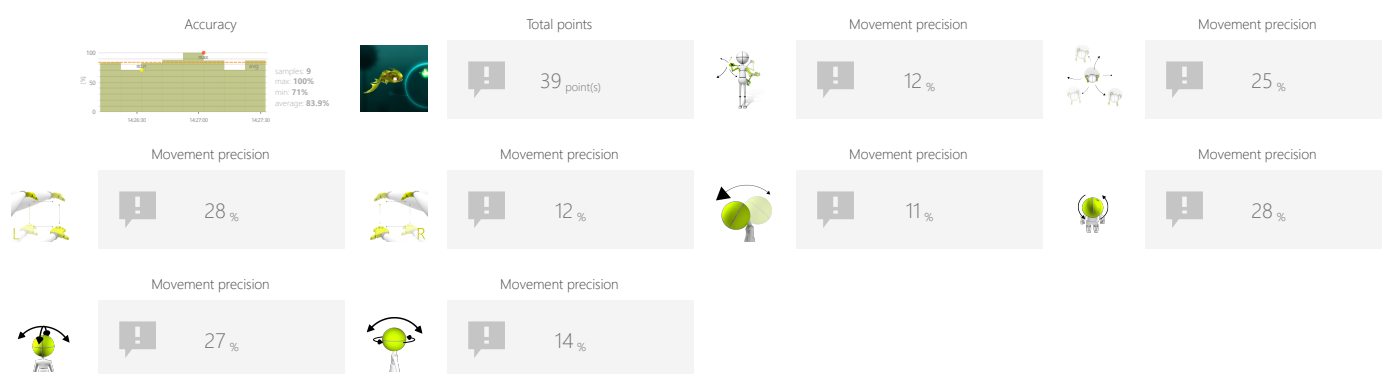
FISH

Measure and train individual's skills to perform specific movement patterns with predefined speed and range.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Movement mode
- Range
- Route shape
- Speed of objects

OBJECTIVES

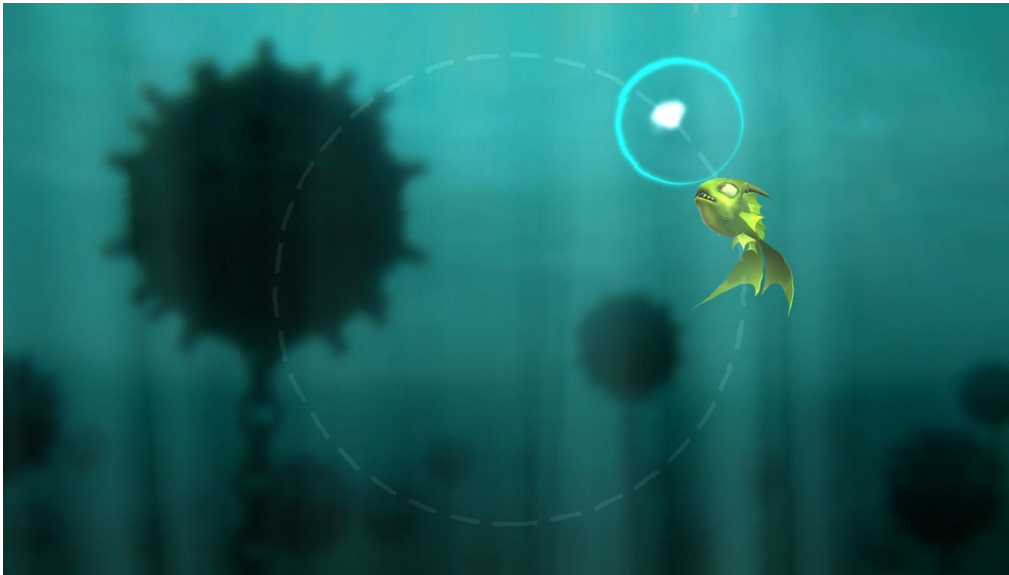
- 3D space movements reproduction
- Planned movements
- Muscle strengthening
- Movement precision
- Visual motor coordination

INSTRUCTION FOR PATIENT

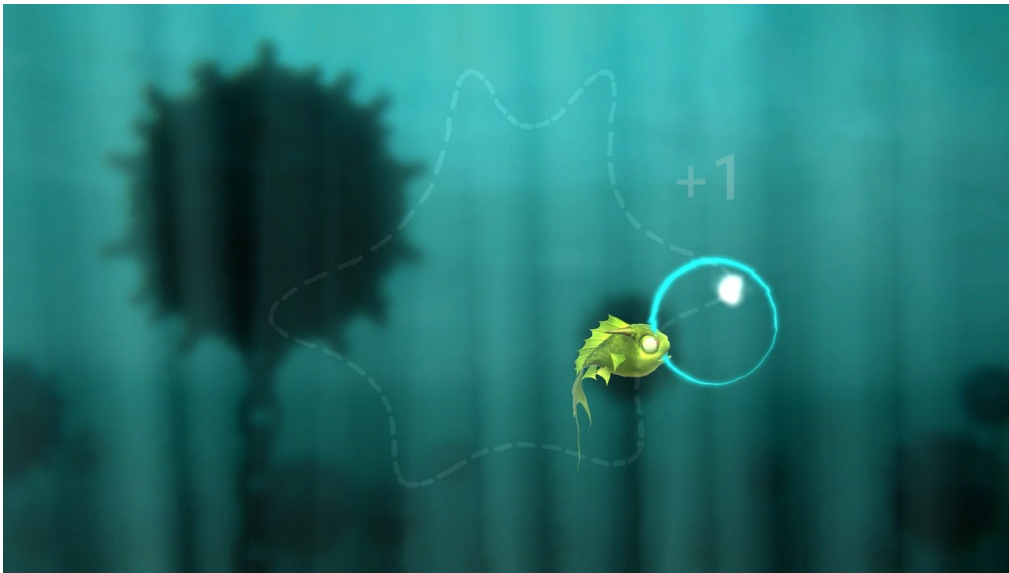
Move the blue circle to protect the sparks source from the fish.
When the sparks source is inside the circle it is safe.



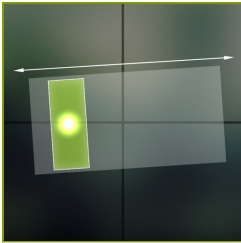
SAMPLE SETTINGS



Difficulty custom	
Duration 90s	Movement mode Left
Range 20% ↔ 80%	Route shape
Speed of objects 100%	



Difficulty 1/3	
Duration 90s	Movement mode Left
Range 20% ↔ 80%	Route shape
Speed of objects 100%	

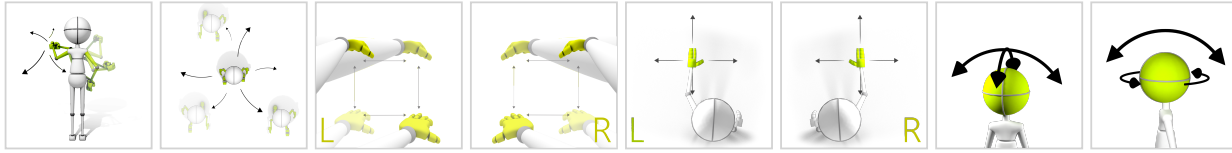


MOVEMENT PRECISION

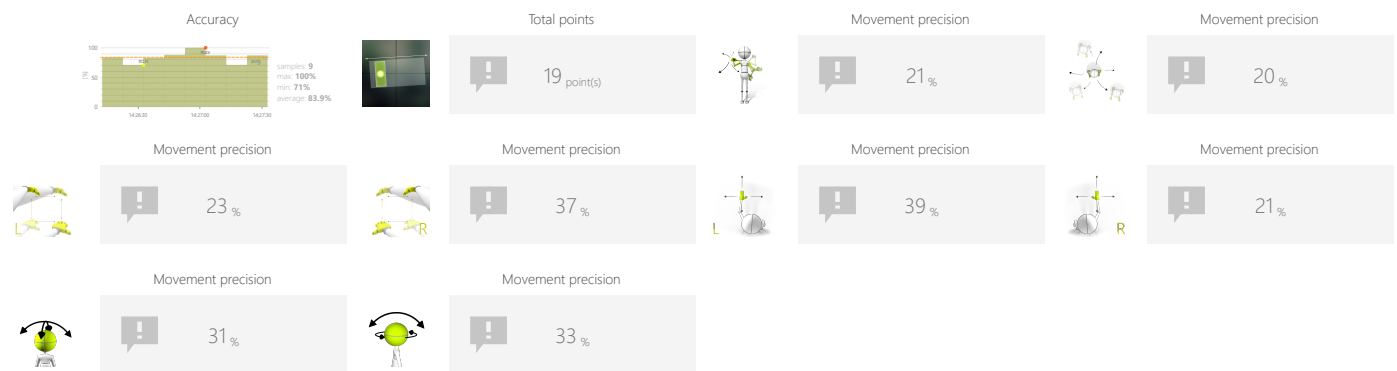
PENDULUM

Measure and train individual's skills to perform specific movement patterns with predefined speed and range.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Show path
- Period
- Rotation
- Pendulum height
- Pendulum width

OBJECTIVES

- 3D space movements reproduction
- Balance and equilibrium training
- Rhythmicity
- Activity in a given rhythm
- Movement precision

INSTRUCTION FOR PATIENT

Try to synchronize yourself with the rectangle movements. Do your best to stay within the rectangle.


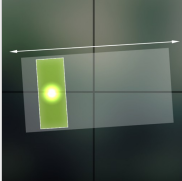



MOVEMENT PRECISION

PENDULUM


SAMPLE SETTINGS








Difficulty
1/2



Duration
< 90s >

Range
80%
20% ↔ 80%


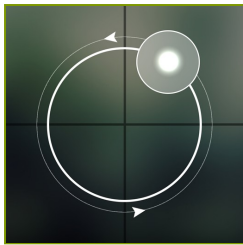
Show path
< No >

Period
< 5s >

Rotation
< 0 >

Pendulum height
< 50% >

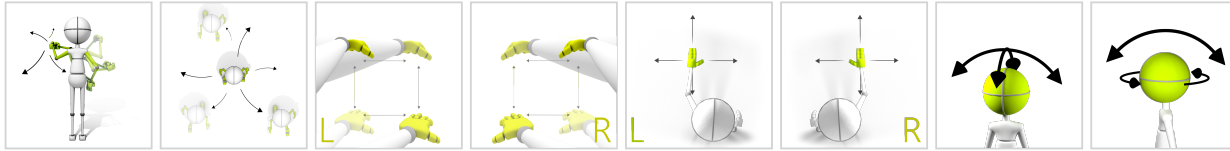
Pendulum width
< 100% >



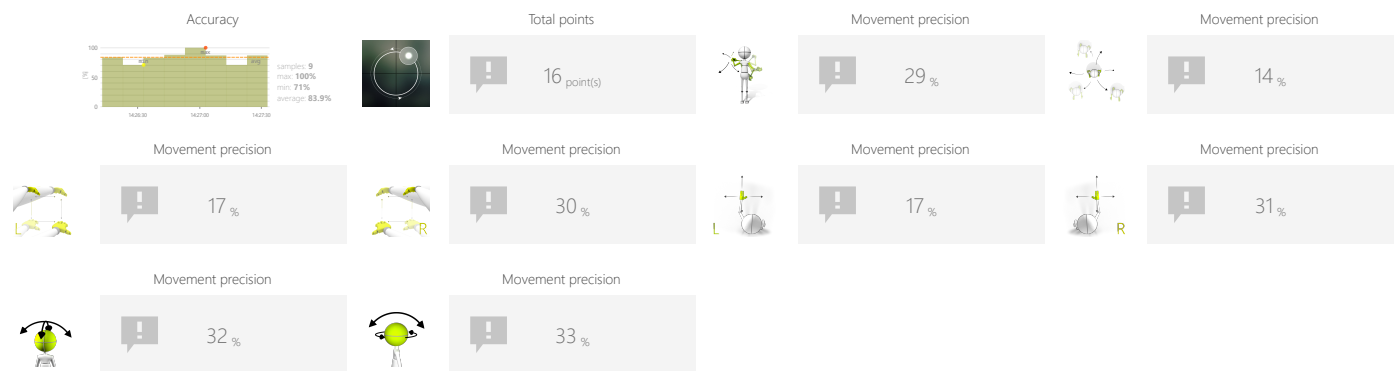
MOVEMENT PRECISION TRACKING

Measure and train individual's skills to perform specific movement patterns with predefined speed and range.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Inverse direction
- Show path
- Period
- Radius
- Target radius

OBJECTIVES

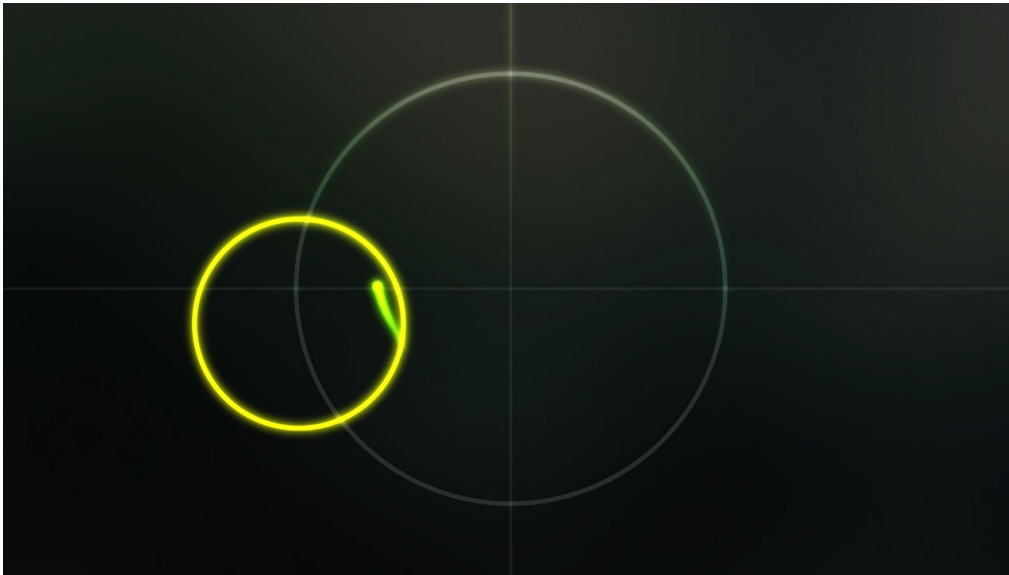
- 3D space movements reproduction
- Balance and equilibrium training
- Test the limits of balance and equilibrium



INSTRUCTION FOR PATIENT

Try to synchronize yourself with the circle movements. Do your best to stay within the circle.

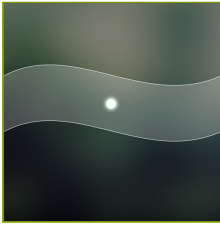


SAMPLE SETTINGS





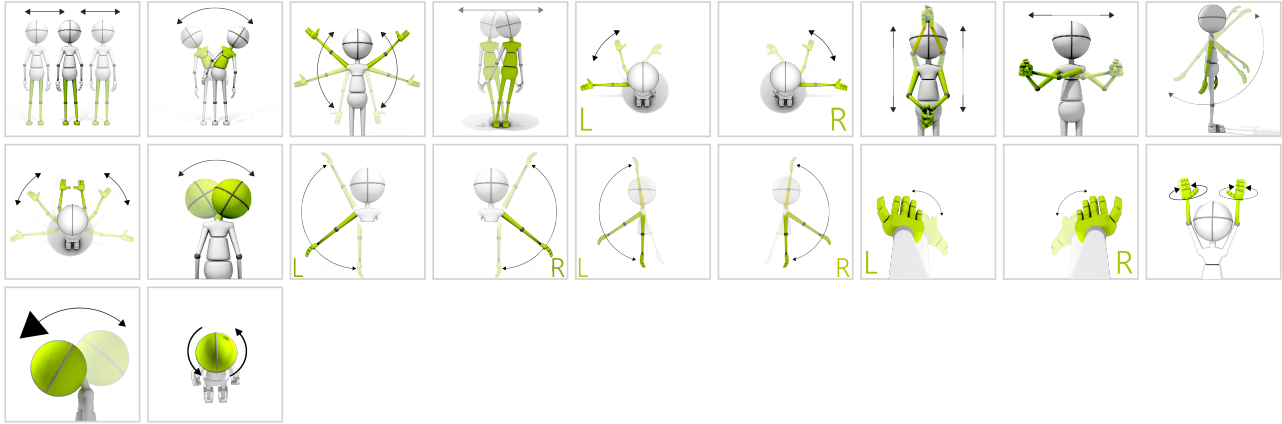
Duration	Range
< 90s >	20% 80% 20% 80%
Inverse direction	Show path
< No >	< No >
Period	Radius
< 10s >	< 75% >
Target radius	
< 75% >	



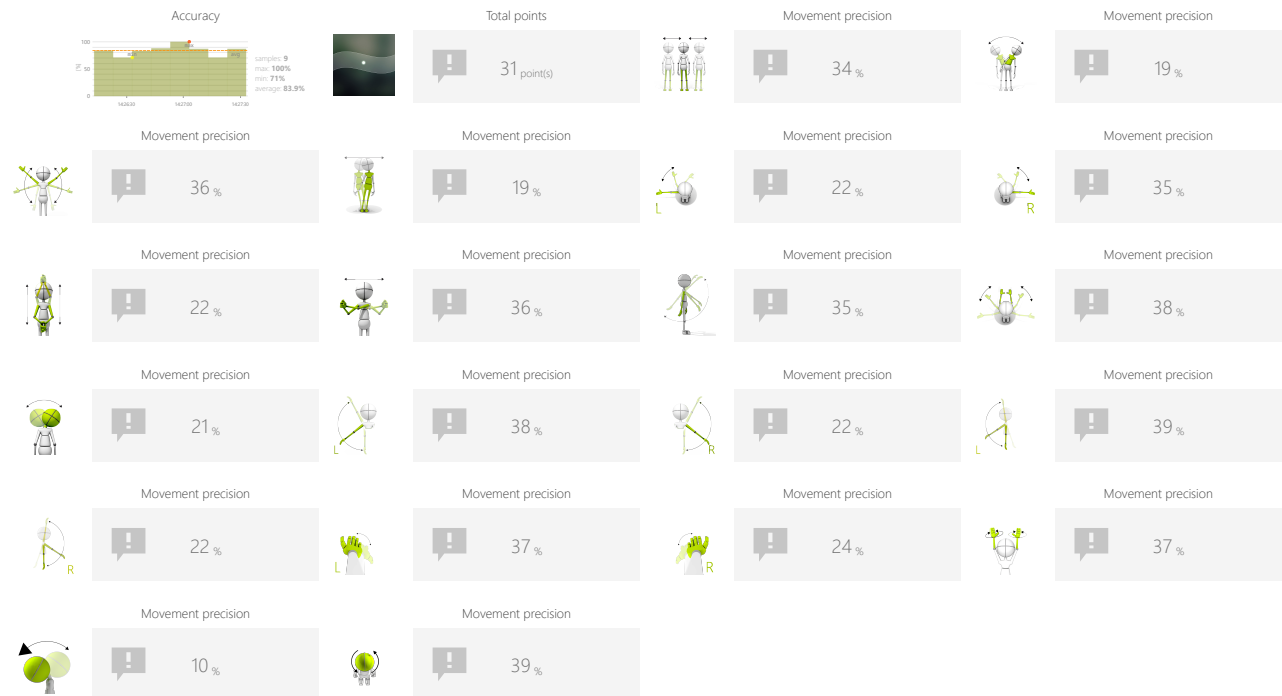
MOVEMENT PRECISION GRAPH

Measure and train individual's skills to perform specific movement patterns with predefined speed and range.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Graph shape (sinus or square, amplitude, border, etc.)
- Task duration
- Range

OBJECTIVES

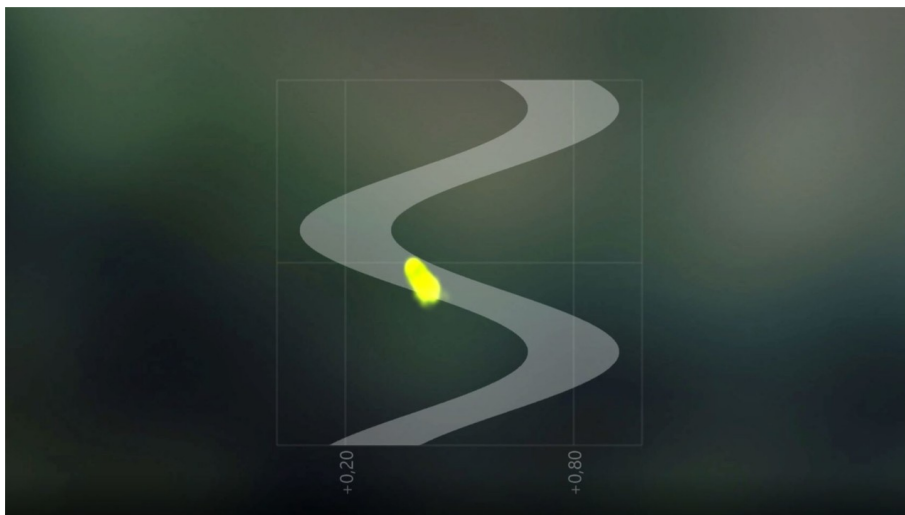
- Movement precision
- Activity in a given rhythm
- Repetitive movements
- Hands raising

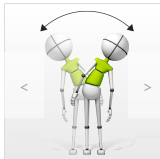
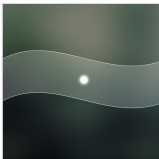
INSTRUCTION FOR PATIENT

Try to stay within the borders.



SAMPLE SETTINGS





◀

Difficulty
3/3

▶

Graph configuration

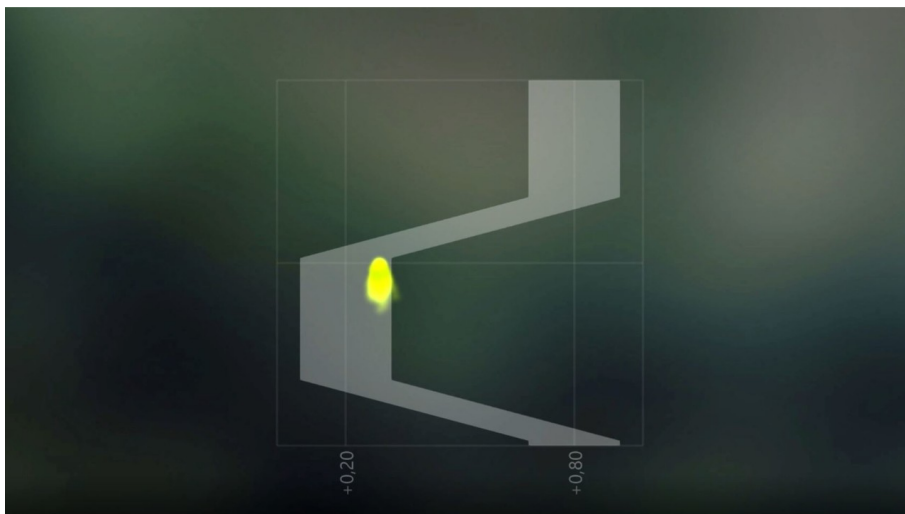
⌚ : 4.0s ± : 20%


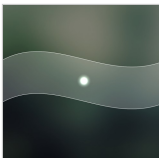
Duration

< 30s >

Range

< 20% ↔ 80% >





◀

Difficulty
1/3

▶

Graph configuration

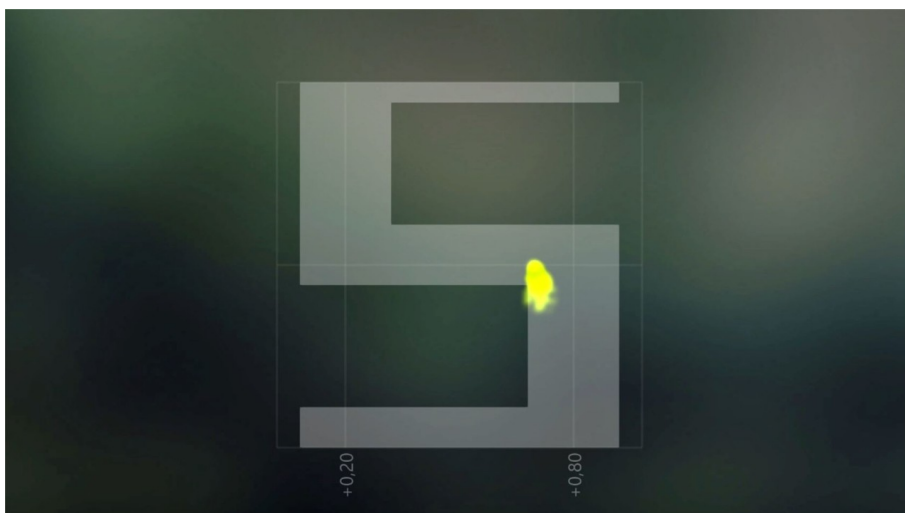
⌚ : 4.0s ± : 40%

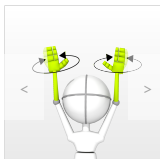
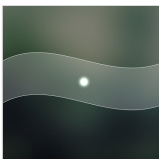
Duration

< 90s >

Range

< 20% ↔ 80% >





◀

Difficulty
custom

▶

Graph configuration

± : 20% ↑ : 2.0s ↓ : 2.0s ↗ : 1.0s ↘ : 1.0s

Duration

< 30s >

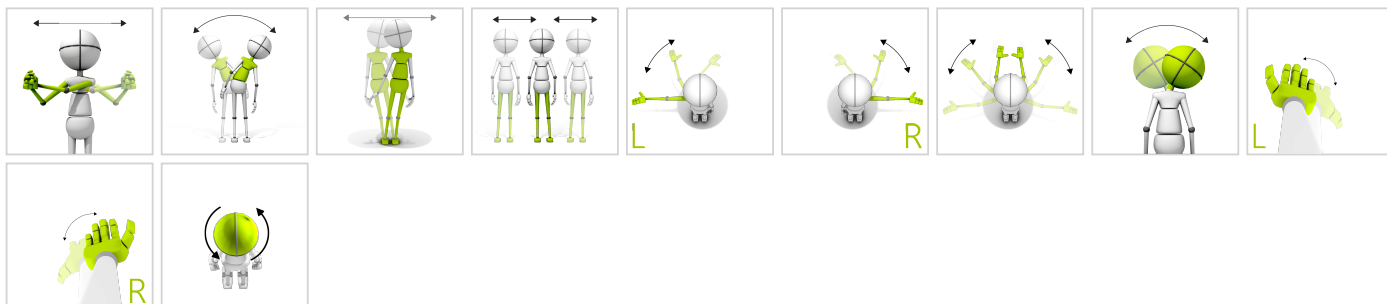


MOVEMENT PRECISION

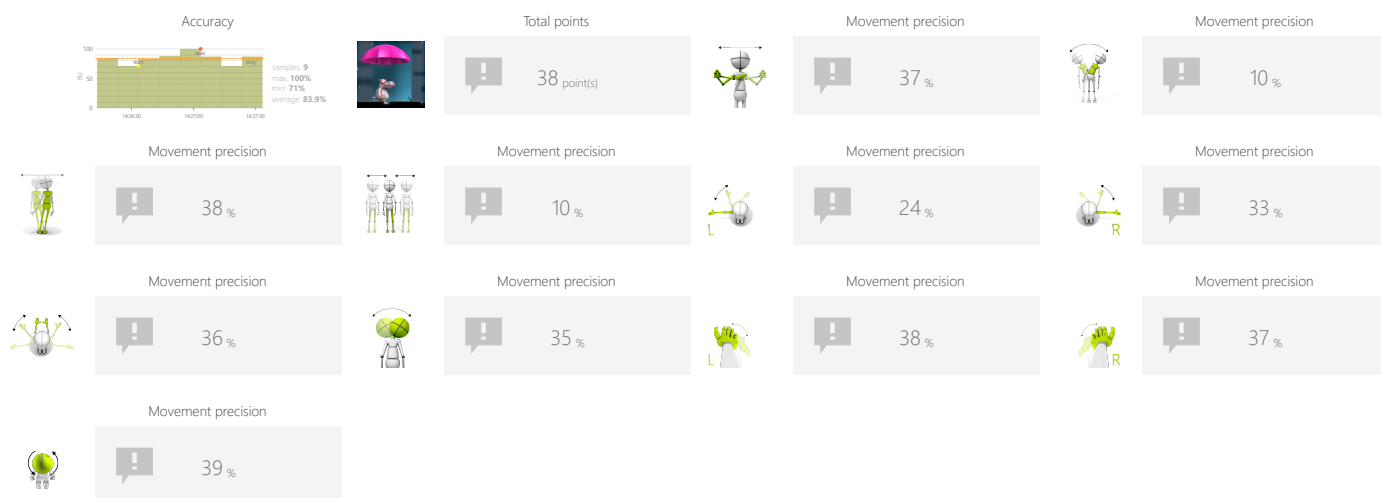
UMBRELLA

Measure and train individual's skills to perform specific movement patterns with predefined speed and range.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Path
- Range
- Umbrella size

OBJECTIVES

- Movement precision
- Visual motor coordination

INSTRUCTION FOR PATIENT

Don't let the hippo get wet - keep the umbrella above him!



MOVEMENT PRECISION

UMBRELLA

SAMPLE SETTINGS



◀	Difficulty 1/3	▶
Duration 60s		Path ⌚: 8.0s
Range 20% ↔ 80%		Umbrella size 150%

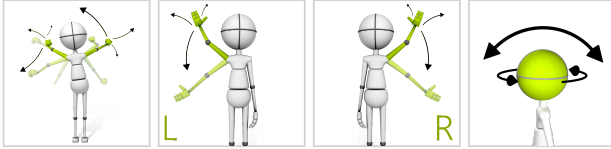


FUNCTIONAL MOVEMENTS

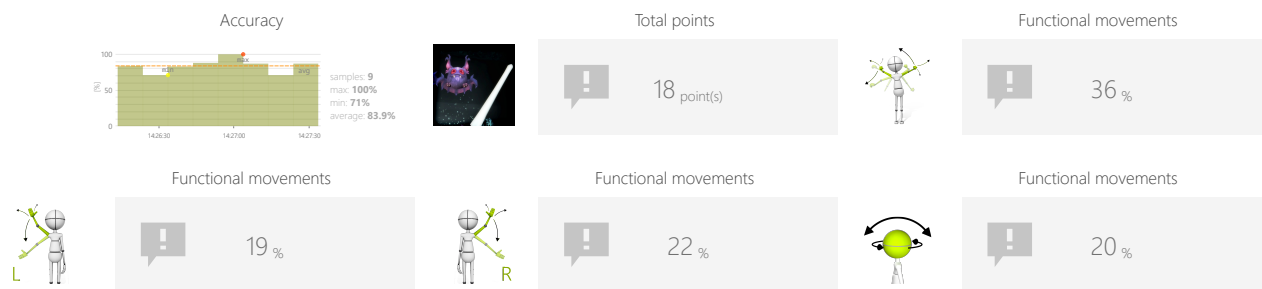
VAMPIRES

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Positions to have targets on
- Task duration
- Time between objects
- Time to react

OBJECTIVES

- Visual motor coordination
- Exercise with or without support from healthy limb
- Spontaneous movements in 3D space
- Speed of movement

INSTRUCTION FOR PATIENT

Use your sword to knock down flying vampires who want to bite you!



FUNCTIONAL MOVEMENTS

VAMPIRES

SAMPLE SETTINGS



◀	Difficulty 1/3	▶
Active positions 		Duration < 90s >
Time between objects < 2s >		Time to react < 2s >



◀	Difficulty 1/3	▶
Active positions 		Duration < 90s >
Time between objects < 2s >		Time to react < 2s >

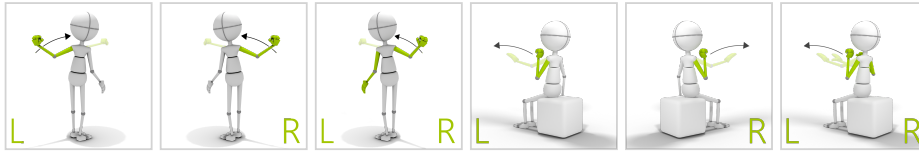


FUNCTIONAL MOVEMENTS

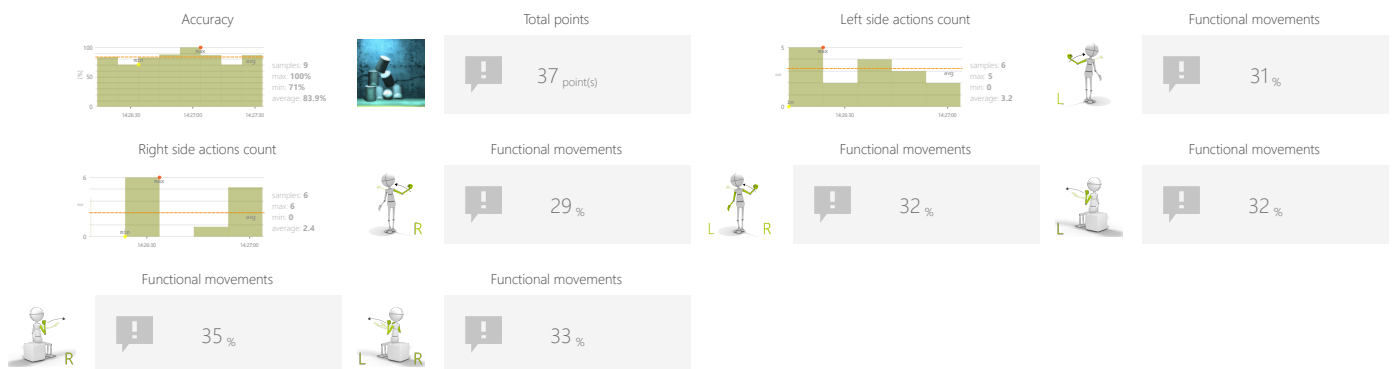
CANS

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Speed of objects
- Weight of targets

OBJECTIVES

- Movement precision
- Predicting the trajectory of objects in 3D space
- Dynamics of planned movements
- Dynamic responses to emerging moving targets
- The ability of spatial visualization



INSTRUCTION FOR PATIENT



Throw the balls to strike as many cans as you can.

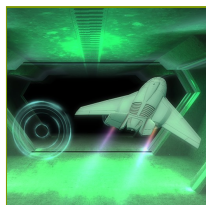


SAMPLE SETTINGS





	Difficulty 1/4	
Duration 90s		Speed of objects 75%
		Weight of targets 100%

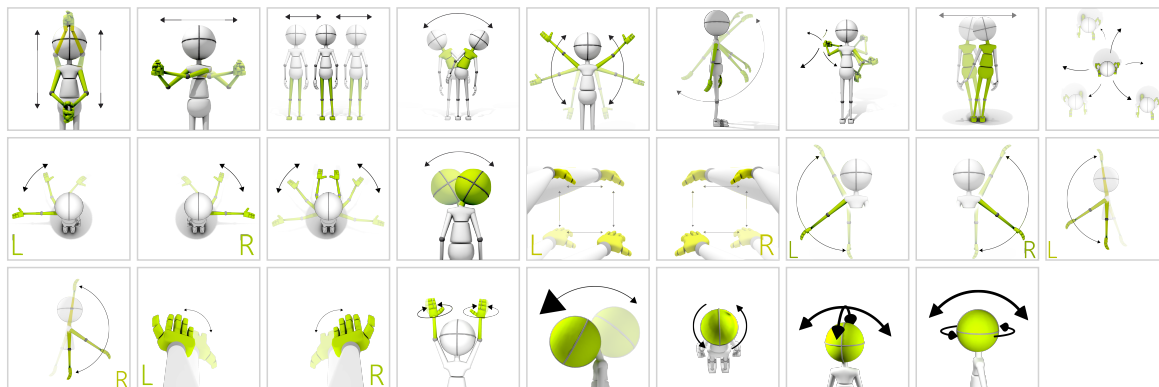


FUNCTIONAL MOVEMENTS

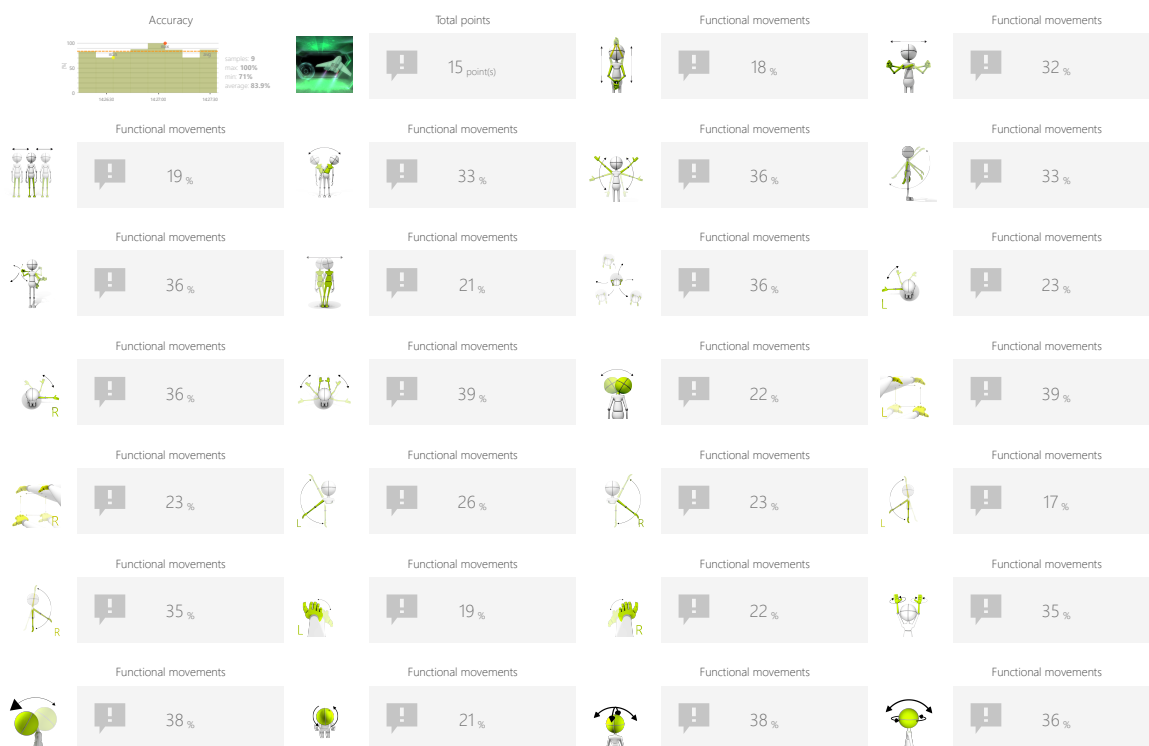
AIRPLANE

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Speed
- Task duration
- Range

OBJECTIVES

- Focusing
- Perceptivity
- Movement precision
- Predicting the trajectory of objects in 3D space
- Balance and equilibrium training

INSTRUCTION FOR PATIENT

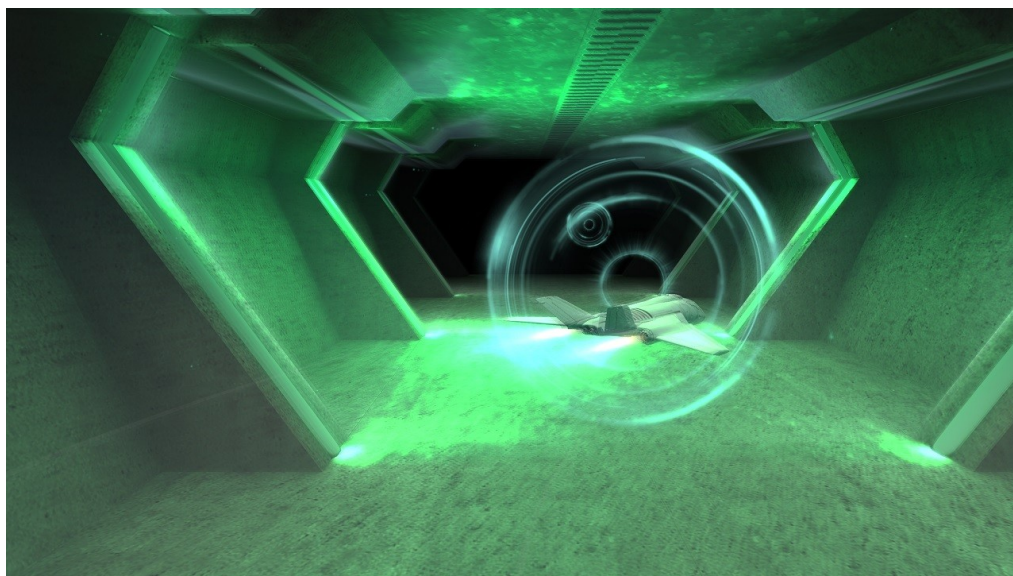
Make the airplane fly through the circles. The closer to the center it flies the more points you get.

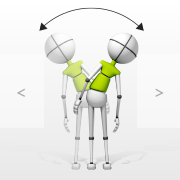
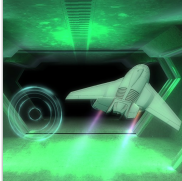


FUNCTIONAL MOVEMENTS

AIRPLANE

SAMPLE SETTINGS





◀

Difficulty
2/4

▶

Speed

< 100% >

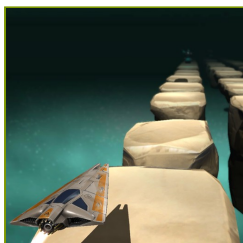
speed set automatically

Duration

< 90s >

Range

< 20% ↔ 80% >

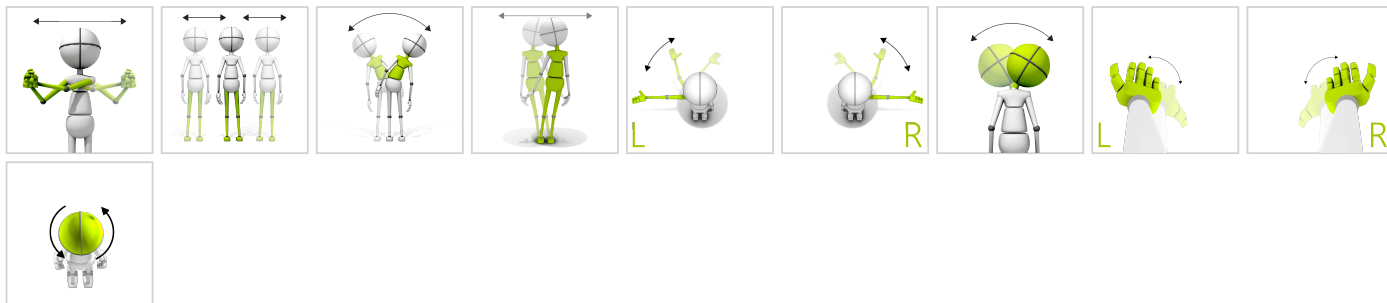


FUNCTIONAL MOVEMENTS

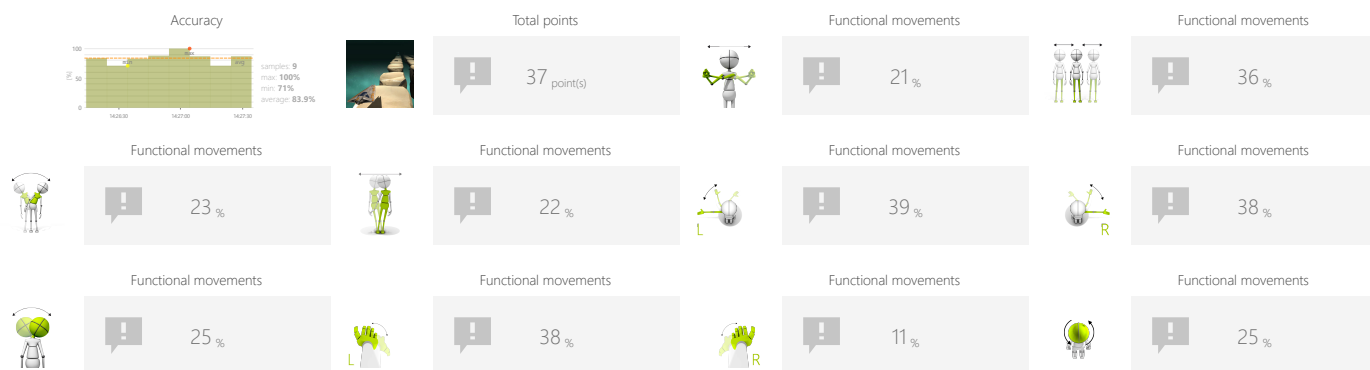
STONES

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Speed
- Task duration
- Range

OBJECTIVES

- Perceptivity
- Dynamics of planned movements
- Reaction to the positive visual stimuli
- Response to negative visual stimuli

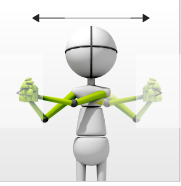
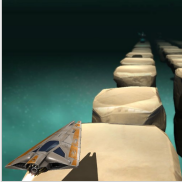
INSTRUCTION FOR PATIENT

Make the the spaceship collect the colorful creatures and avoid the rocks.



SAMPLE SETTINGS





◀

Difficulty
1/3

▶

Speed

< 100% >


speed set automatically

Duration

< 90s >

Range

< 20% ↔ 80% >



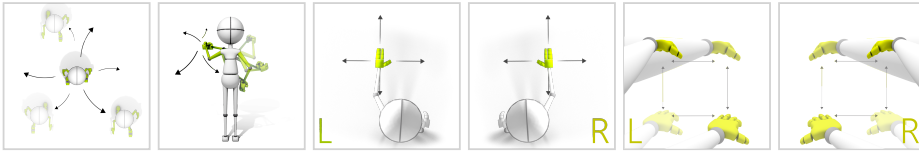


FUNCTIONAL MOVEMENTS

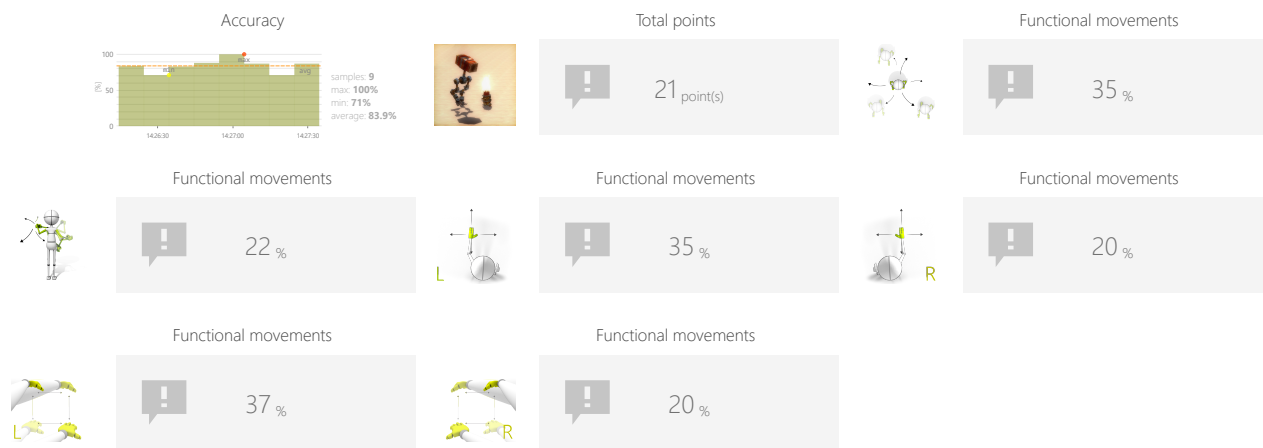
HAMMER

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Positions to have targets on
- Task duration
- Range
- Time to react
- Reticle size

OBJECTIVES

- Planning and Strategy
- Sideways walking
- Balance and equilibrium training
- Speed of decision making

INSTRUCTION FOR PATIENT

Hit the burning barrels as quickly as you can. Then return to the center.


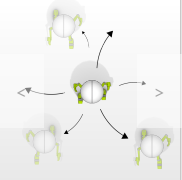






FUNCTIONAL MOVEMENTS

HAMMER

SAMPLE SETTINGS



		
	Difficulty 1/3	
Active positions 		Duration 90s
Range 		Time to react 10s
		Reticle size 125%

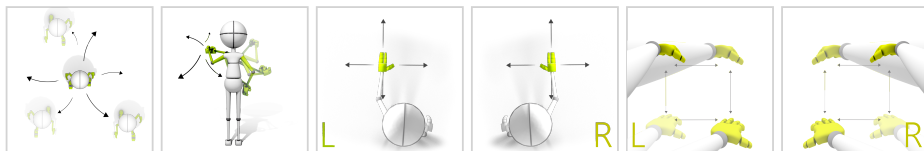


FUNCTIONAL MOVEMENTS

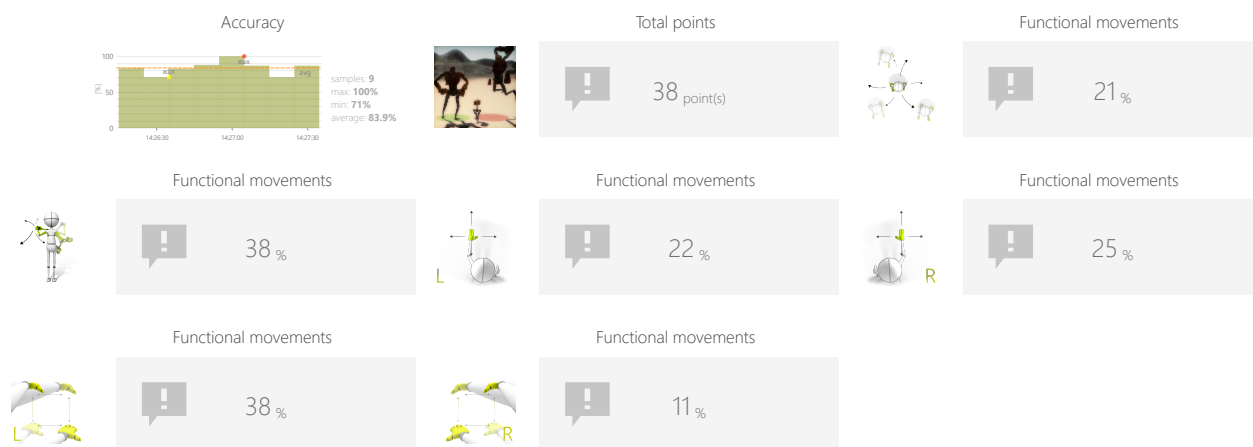
RUNAWAY

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Number of enemies
- Enemies speed

OBJECTIVES

- Predicting the trajectory of objects in 3D space
- Response to negative visual stimuli
- Focusing
- Perceptivity
- Balance and equilibrium training

INSTRUCTION FOR PATIENT

Keep away from the big robots.

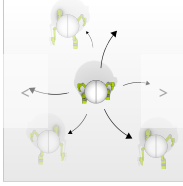



FUNCTIONAL MOVEMENTS

RUNAWAY

SAMPLE SETTINGS





◀

Difficulty

▶

1/3

Duration

90s

Range

30% ↔ 70%

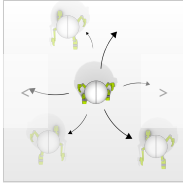

Number of enemies

2

Enemies speed

100%





◀

Difficulty

▶

custom

Duration

90s

Range

30% ↔ 70%

Number of enemies

4

Enemies speed

100%



FUNCTIONAL MOVEMENTS

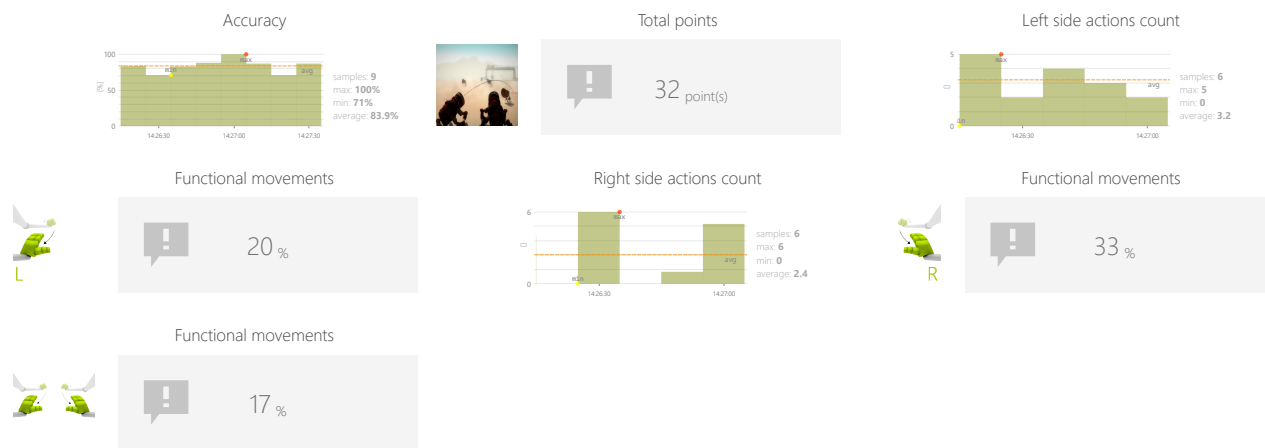
CANNON

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Time between cannonballs
- Time between enemies
- Enemies speed

OBJECTIVES

- Planning and Strategy
- Movement precision
- Predicting the trajectory of objects

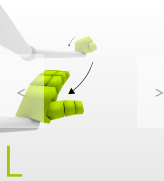

INSTRUCTION FOR PATIENT

Use the cannon(s) to shoot into the robots coming in your direction.



SAMPLE SETTINGS





◀

Difficulty
1/3

▶



Duration
< 90s >

Time between cannonballs
< 2s >

Time between enemies
< 4s >

Enemies speed
< 50% >





◀

Difficulty
custom

▶

Duration
< 90s >

Time between cannonballs
< 2s >

Time between enemies
< 4s >

Enemies speed
< 100% >

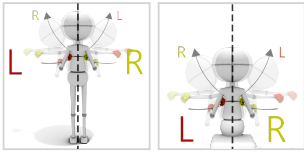


FUNCTIONAL MOVEMENTS

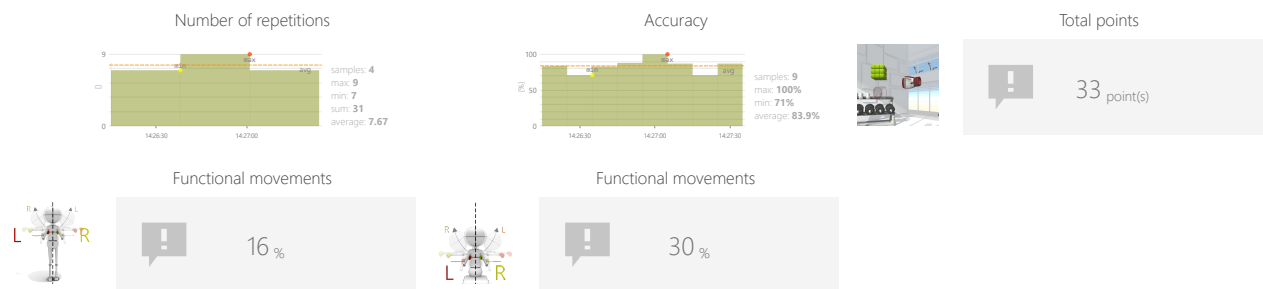
CROSS PUNCHER

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Time to react
- Distance to targets

OBJECTIVES

- Crossing the midline
- Speed of movement
- Rhythmicity
- Repetitive movements

INSTRUCTION FOR PATIENT

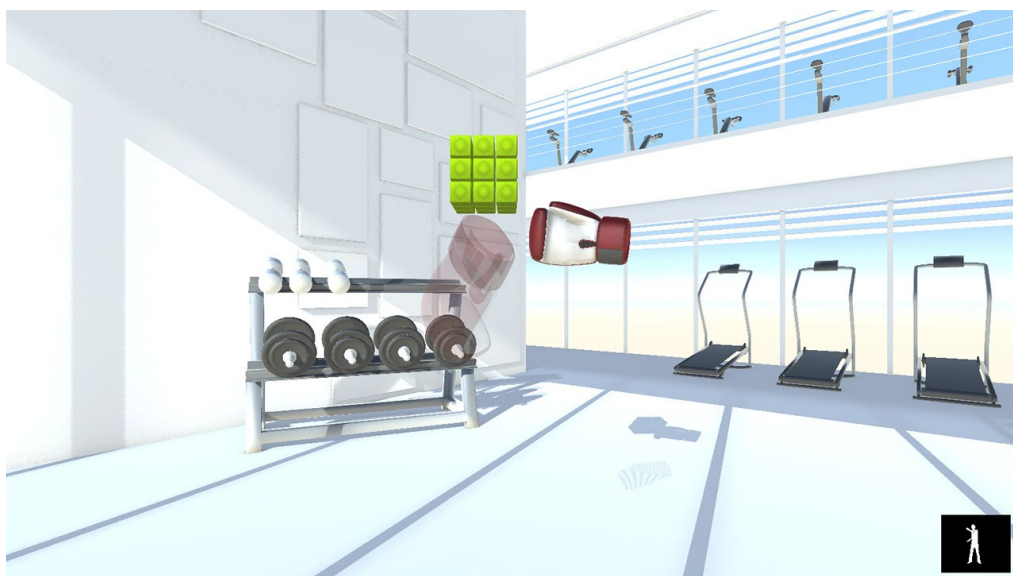
Hit green cubes as fast as you can and remember to always cross your punches and kicks.



FUNCTIONAL MOVEMENTS

CROSS PUNCHER

SAMPLE SETTINGS



◀	Difficulty 1/3	▶
Duration < 30s >		Time to react < 3s >
Distance to targets < 75% >		

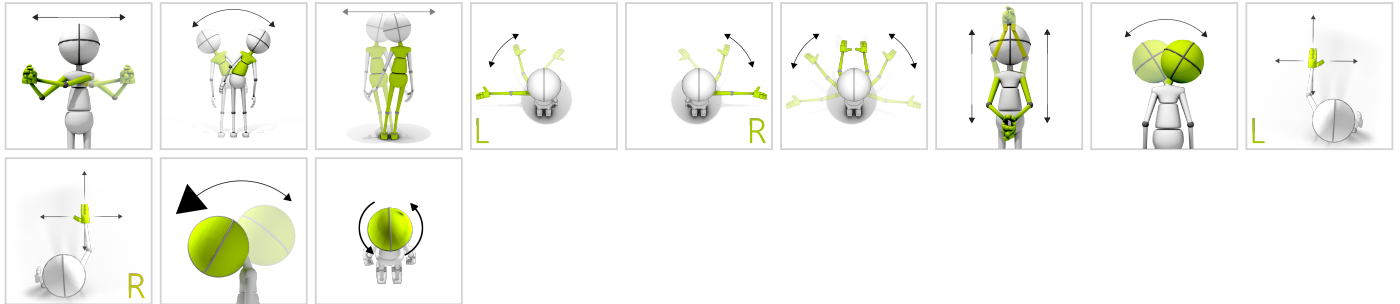


FUNCTIONAL MOVEMENTS

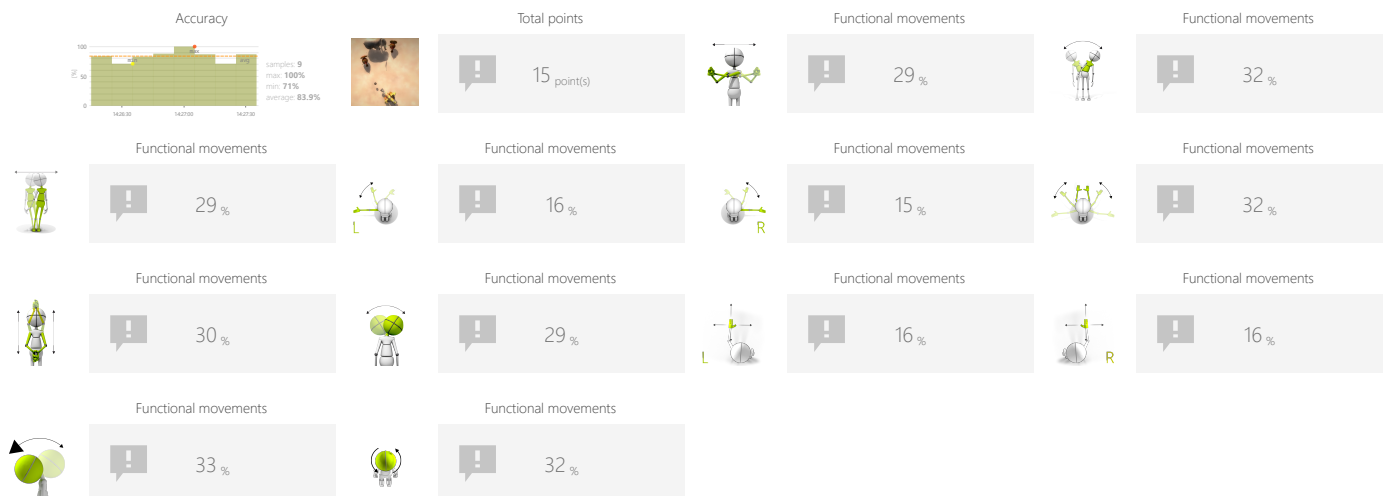
AUTOMATIC CANNON

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Enable distractors
- Time between cannonballs
- Time between enemies
- Enemies speed

OBJECTIVES

- Divided attention
- Spontaneous movements
- Arms swings
- Muscle strengthening

INSTRUCTION FOR PATIENT

Control cannon(s) to destroy robots, but avoid hitting the elephant!






FUNCTIONAL MOVEMENTS

AUTOMATIC CANNON


SAMPLE SETTINGS







Difficulty
1/3



Duration

< 90s >

Range

< 20% ↔ 80% >

Enable distractors

< No >

Time between cannonballs

< 1s >



Time between enemies


< 3s >

Enemies speed


< 50% >







Difficulty
custom



Duration

< 90s >

Range

< 20% ↔ 80% >

Enable distractors

< No >

Time between cannonballs

< 1s >

Time between enemies

< 3s >

Enemies speed

< 100% >

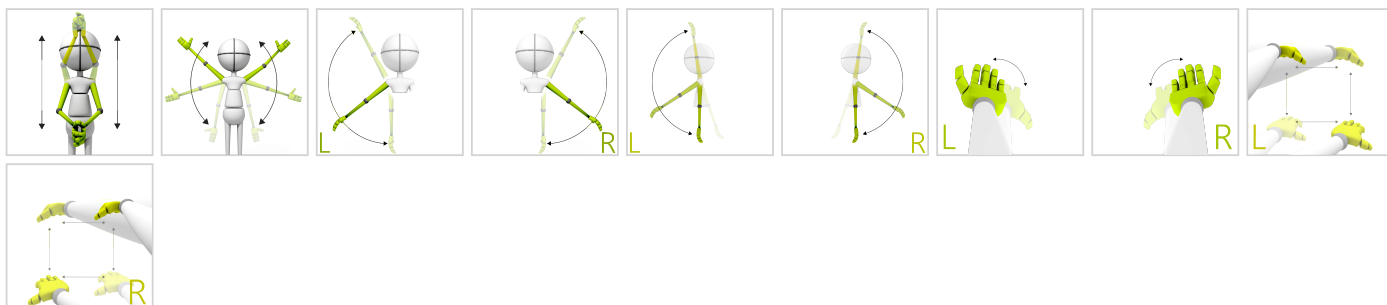


FUNCTIONAL MOVEMENTS

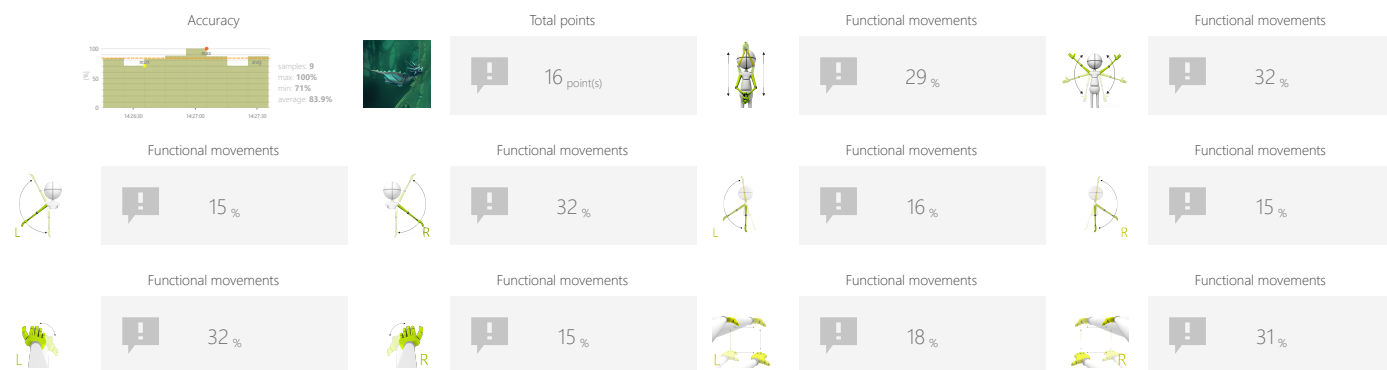
DRAGON

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Coins group size
- Distance between coins
- Gravity force

OBJECTIVES

- Predicting the trajectory of objects
- Improve range of motion
- Visual motor coordination
- Muscle strengthening
- Planning and Strategy

INSTRUCTION FOR PATIENT

Fly and collect the coins.



FUNCTIONAL MOVEMENTS

DRAGON

SAMPLE SETTINGS



◀	Difficulty custom	▶
Duration 90s		Range 20% 80%
Coins group size 3		Distance between coins 250%
Gravity force 100%		



◀	Difficulty 1/3	▶
Duration 90s		Range 20% 80%
Coins group size 5		Distance between coins 250%
Gravity force 100%		

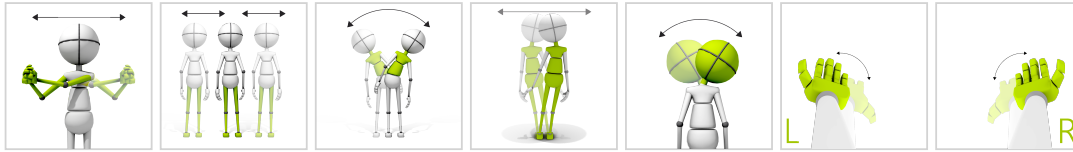


FUNCTIONAL MOVEMENTS

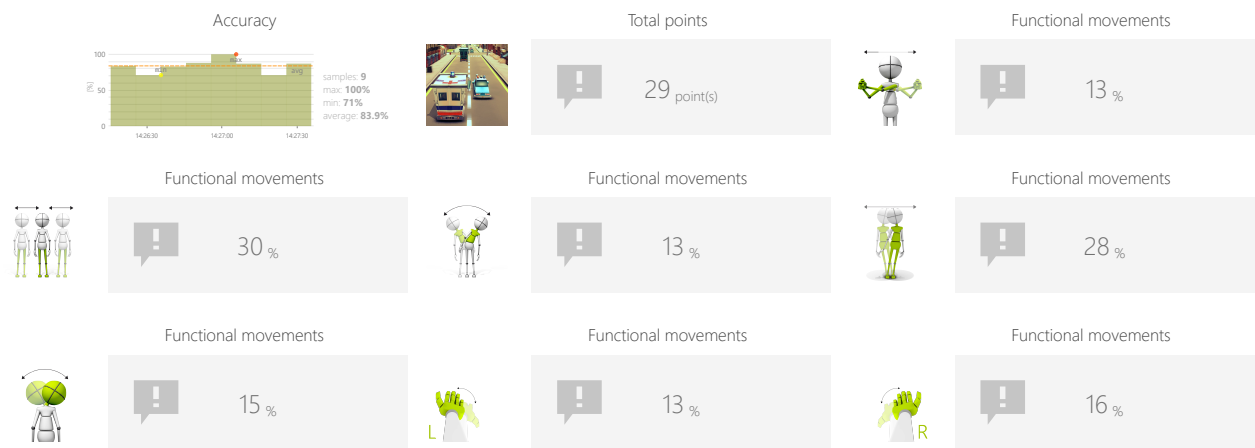
AMBULANCE

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Speed
- Task duration
- Range
- Distance between cars

OBJECTIVES

- Balance and equilibrium training
- Dynamics of planned movements
- Focusing
- Speed of decision making
- Visual motor coordination

INSTRUCTION FOR PATIENT

Go as fast as you can and avoid hitting other cars.





FUNCTIONAL MOVEMENTS

AMBULANCE

SAMPLE SETTINGS





Difficulty

2/3

Speed

50%

speed set automatically

Duration

30s



Range

20% ↔ 80%

Distance between cars

50%





Difficulty

custom

Speed

50%

speed set automatically

Duration

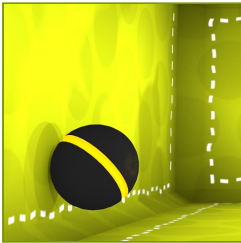
30s

Range

20% ↔ 80%

Distance between cars

200%

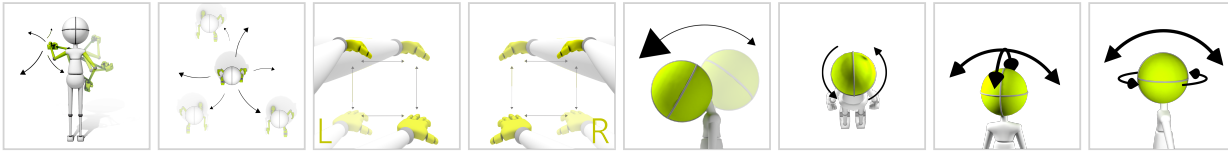


FUNCTIONAL MOVEMENTS

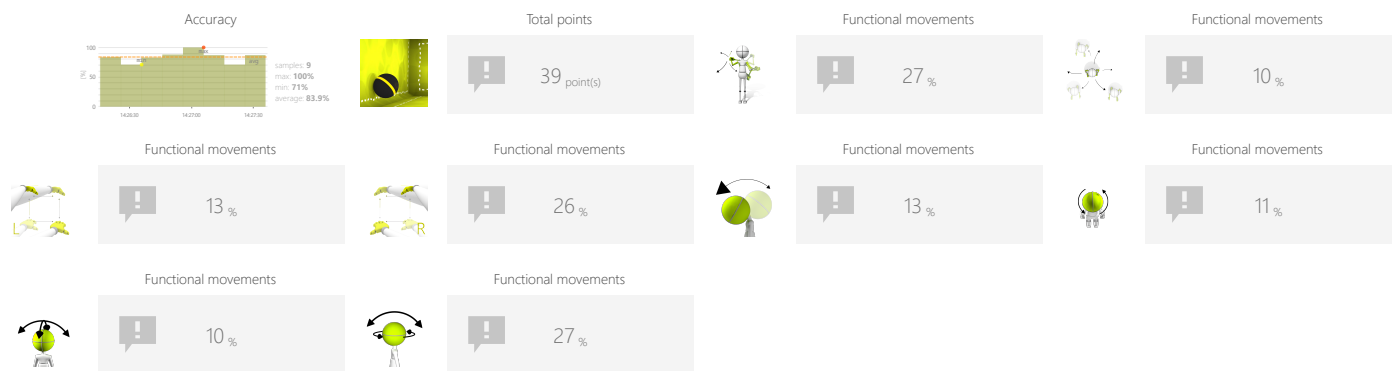
ARCANOID

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Reticle size
- Speed of objects

OBJECTIVES

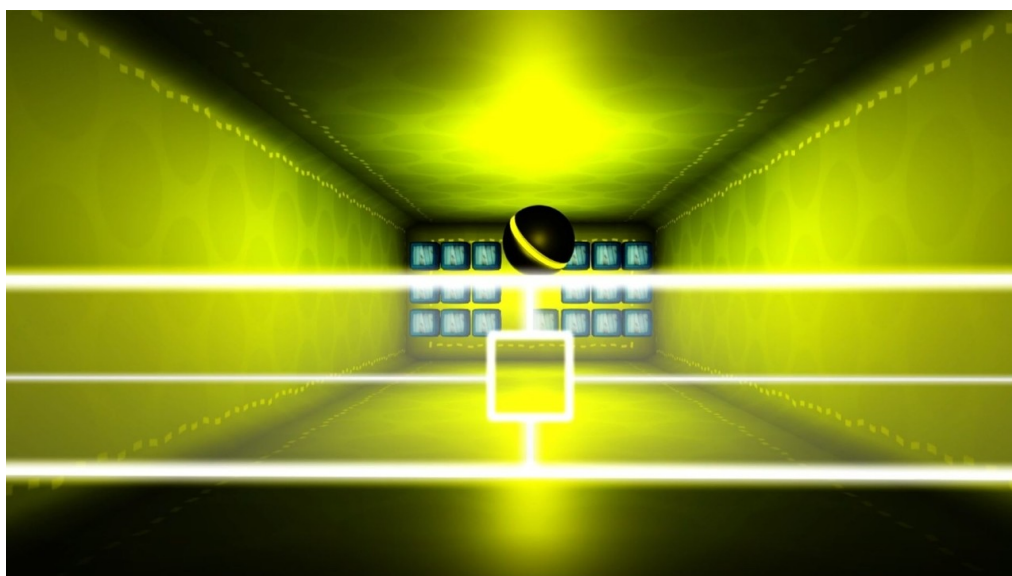
- Dynamics of planned movements
- Predicting the trajectory of objects in 3D space
- Visual motor coordination


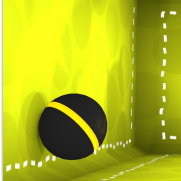
INSTRUCTION FOR PATIENT

Destroy as many boxes as you can.



SAMPLE SETTINGS





◀

Difficulty

▶

custom

◀

Duration

>

90s

◀

Range

>

80%
20% ↔ 80%

◀

Reticle size

>

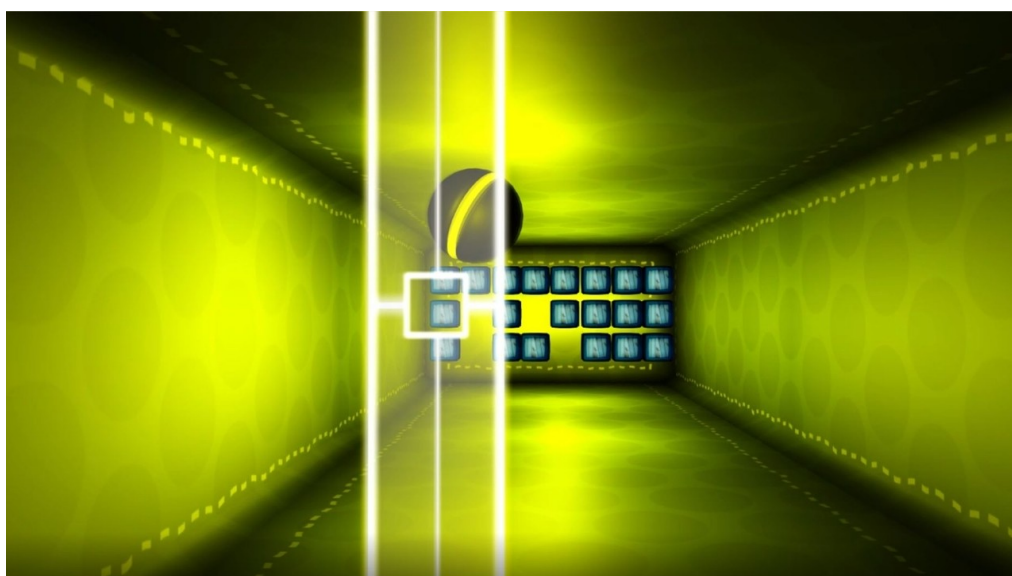
100%


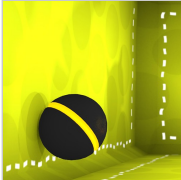
◀

Speed of objects

>

70%





◀

Difficulty

▶

custom

◀

Duration

>

90s

◀

Range

>

80%
20% ↔ 80%

◀

Reticle size

>

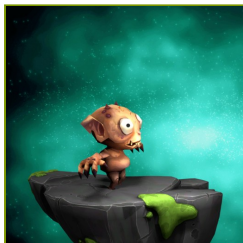
75%

◀

Speed of objects

>

70%



FUNCTIONAL MOVEMENTS

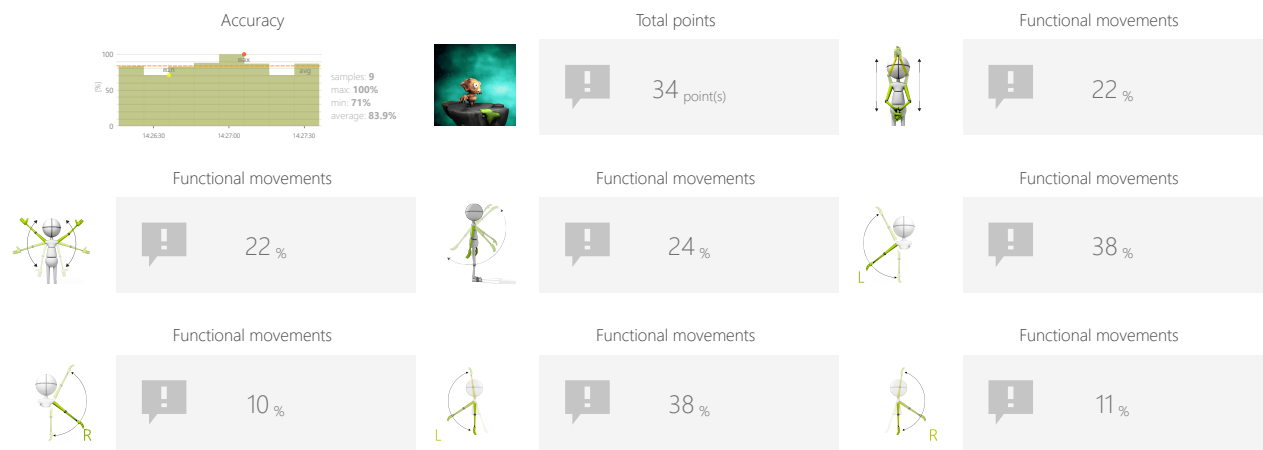
ROCKET JUMPING

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Time between objects
- Bomb format
- Speed of objects

OBJECTIVES

- Spontaneous movements
- Dynamic responses to emerging moving targets
- Predicting the trajectory of objects

INSTRUCTION FOR PATIENT

Help the creature jump over incoming rockets and avoid being hit.

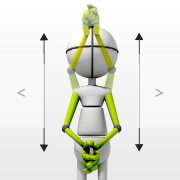
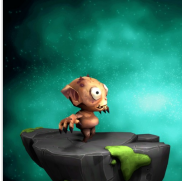


FUNCTIONAL MOVEMENTS

ROCKET JUMPING

SAMPLE SETTINGS





◀

Difficulty

▶

1/3

◀

Duration

▶


90s

◀

Range

▶

20% 80%



◀

Time between objects

▶

5s

◀

Bomb format

▶

1


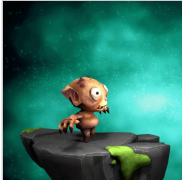
◀

Speed of objects

▶

100%





◀

Difficulty

▶

custom

◀

Duration

▶


90s

◀

Range

▶

20% 80%



◀

Time between objects

▶

5s

◀

Bomb format

▶

2

◀

Speed of objects

▶

100%

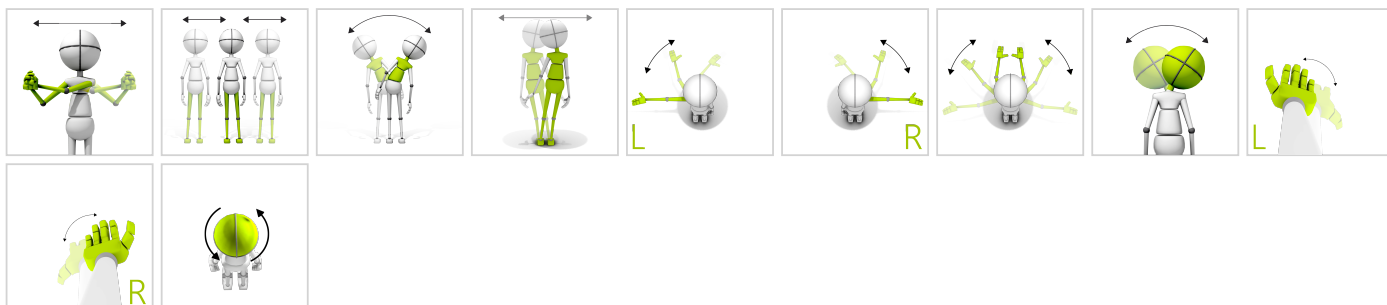


FUNCTIONAL MOVEMENTS

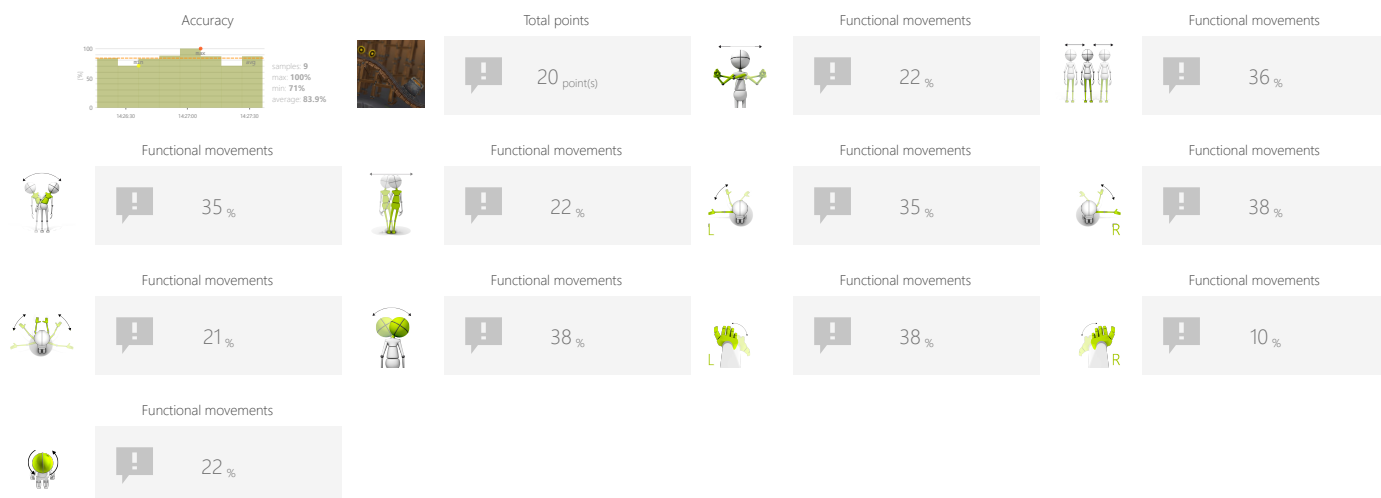
RAILS

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Speed
- Task duration
- Range
- Route shape
- Enable derailling
- Enable obstacles
- Time between objects

OBJECTIVES

- Dynamic responses to emerging moving targets
- Predicting the trajectory of objects
- Visual motor coordination

INSTRUCTION FOR PATIENT

Control the trolley to collect the coins.





FUNCTIONAL MOVEMENTS

RAILS

SAMPLE SETTINGS





◀

Difficulty
1/3

▶

Speed

< 100% >

speed set automatically

Duration

< 90s >

Range

< 20% ↔ 80% >

Route shape

< — >

Enable derailling

< No >



Enable obstacles

< No >

Time between objects

< 5s >





◀

Difficulty
3/3

▶

Speed

< 200% >

speed set automatically

Duration

< 90s >

Range

< 20% ↔ 80% >

Route shape

< ~ >

Enable derailling

< Yes >

Enable obstacles

< No >

Time between objects

< 5s >

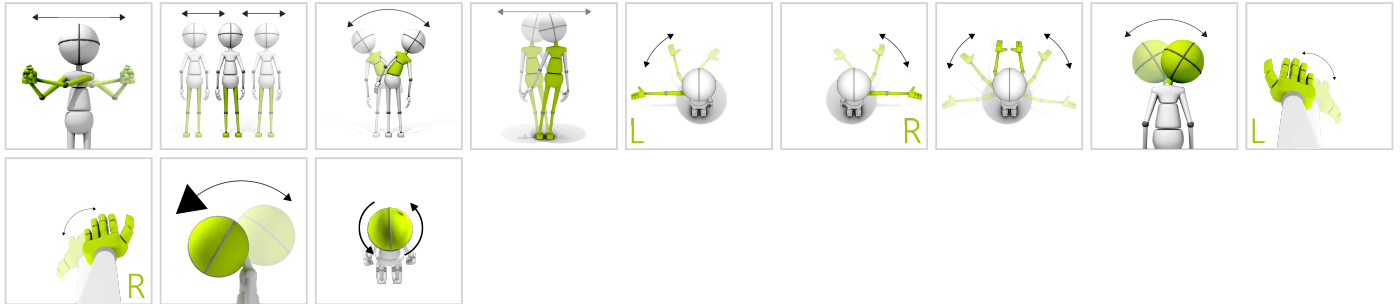


FUNCTIONAL MOVEMENTS

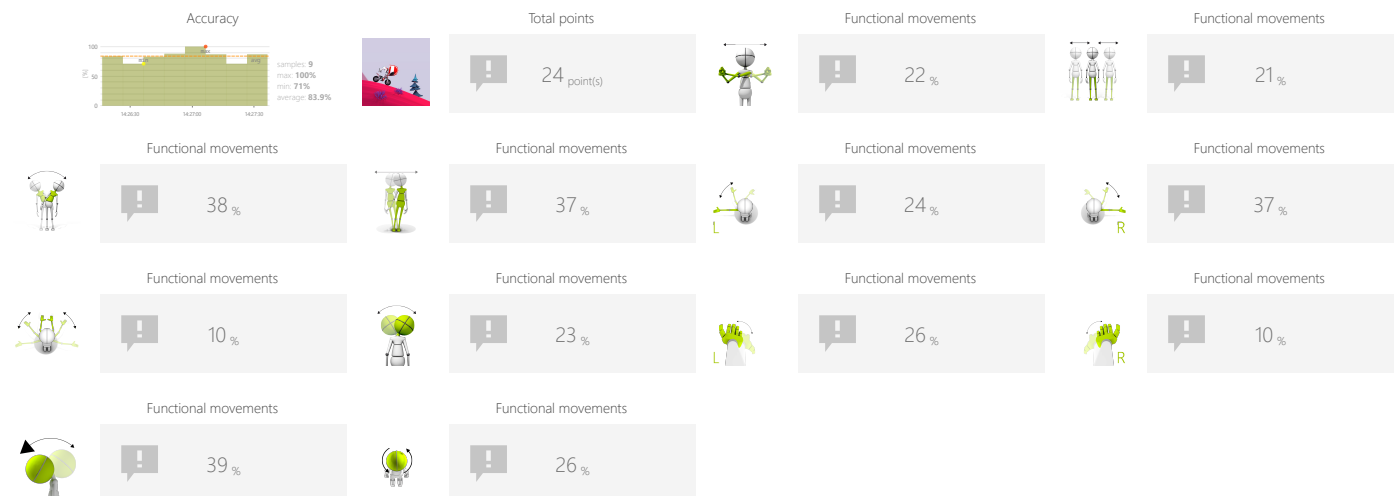
MOTOCROSS

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Route shape

OBJECTIVES

- Dynamics of planned movements
- Planning and Strategy

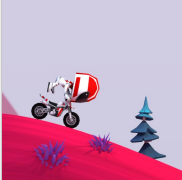



INSTRUCTION FOR PATIENT

Accelerate and brake to cover the entire route as quickly as possible without tipping.



SAMPLE SETTINGS



		
	Difficulty 2/3	
Duration 90s		Range 20% ↔ 80%
Route shape Medium		

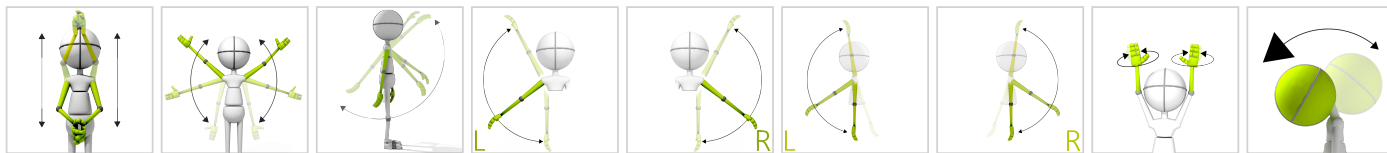


FUNCTIONAL MOVEMENTS

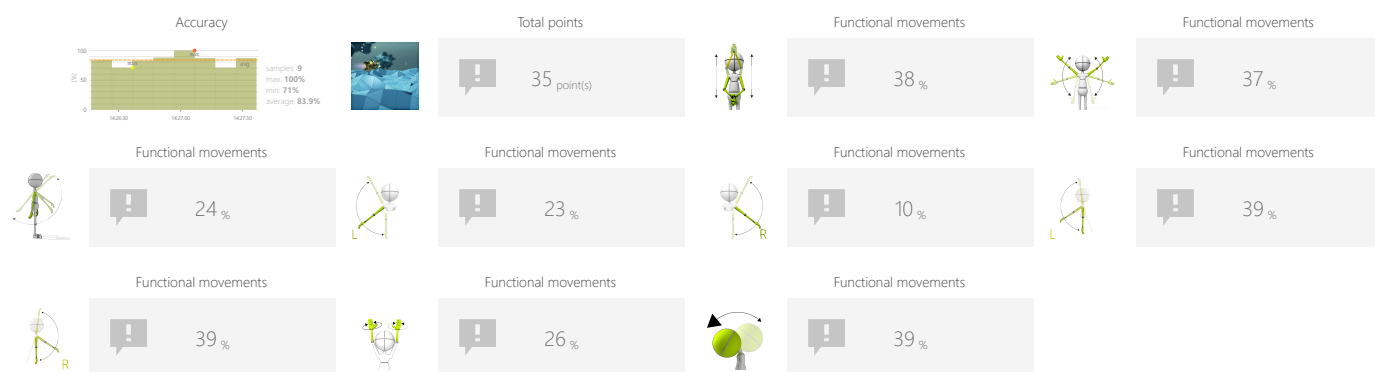
GEOMETRY FLIER

Measure and train individual's skills to perform movements based on real-world situational biomechanics. They usually involve multi-planar, multi-joint movements which place demand on the body's core musculature and innervation.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Speed
- Task duration
- Range

OBJECTIVES

- Dynamics of planned movements
- Activity in a given rhythm
- Visual motor coordination

INSTRUCTION FOR PATIENT

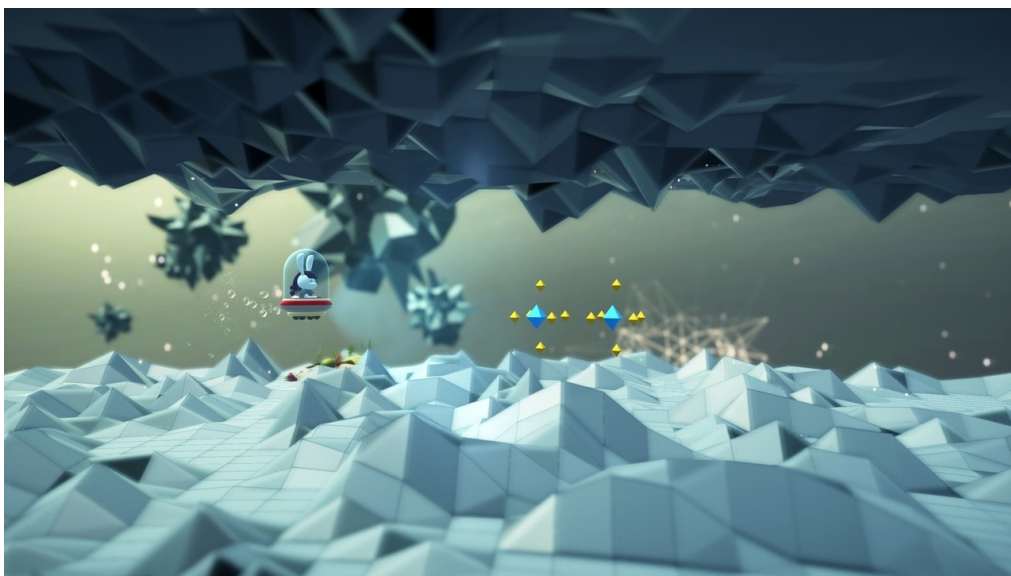
Control the vehicle to avoid the obstacles.

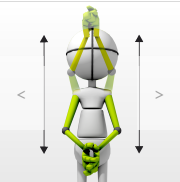



FUNCTIONAL MOVEMENTS

GEOMETRY FLIER

SAMPLE SETTINGS





◀

Difficulty
1/3

▶

<

Speed
100%

>


speed set automatically

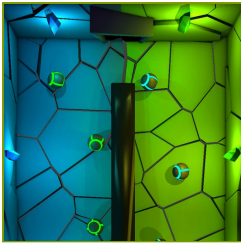
<

Duration
30s

>

Range
20%
80%

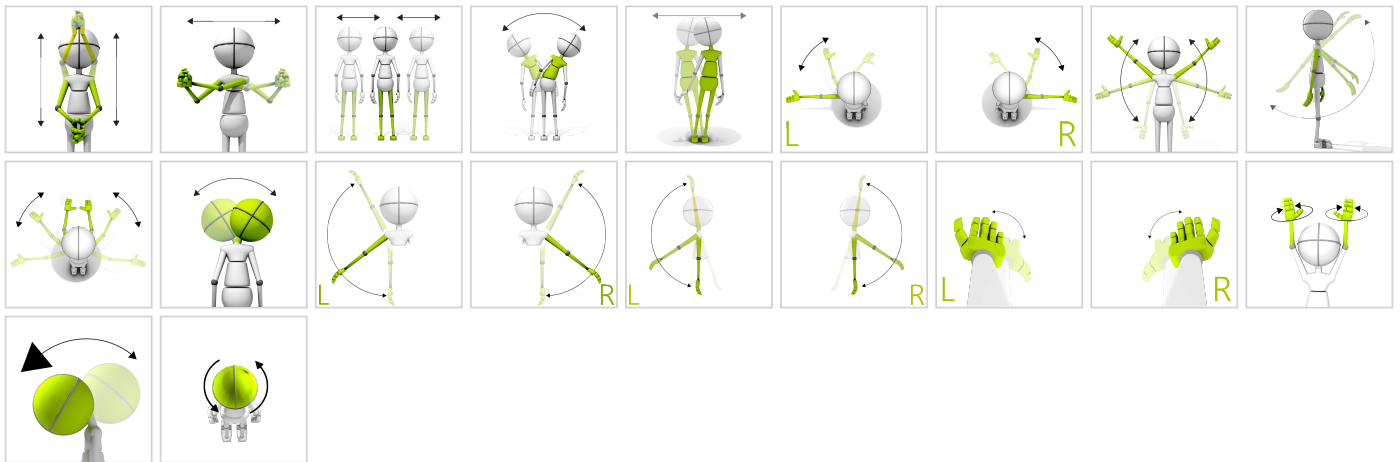




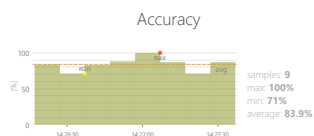
DIVIDED ATTENTION SORTER

Measure and train individual's skills to successfully execute more than one action at a time, while paying attention to two or more channels of information.

CONTROL MODES



RESULTS



Total points

38 point(s)



Divided attention

11 %

ADJUSTMENTS

- Task duration
- Range
- Number of objects
- Gap size
- Speed of objects

OBJECTIVES

- Predicting the trajectory of objects
- Focusing
- Perceptivity
- Movement precision
- Exercise with or without support from healthy limb

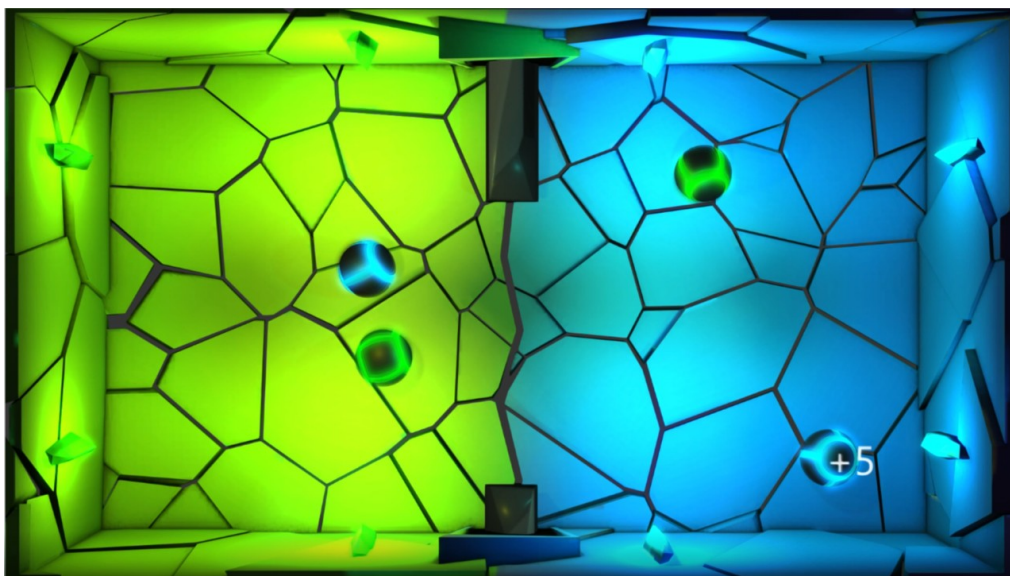
INSTRUCTION FOR PATIENT

Pass or block the balls so that the blue balls are on the blue side and the green balls are on the green side of the screen.

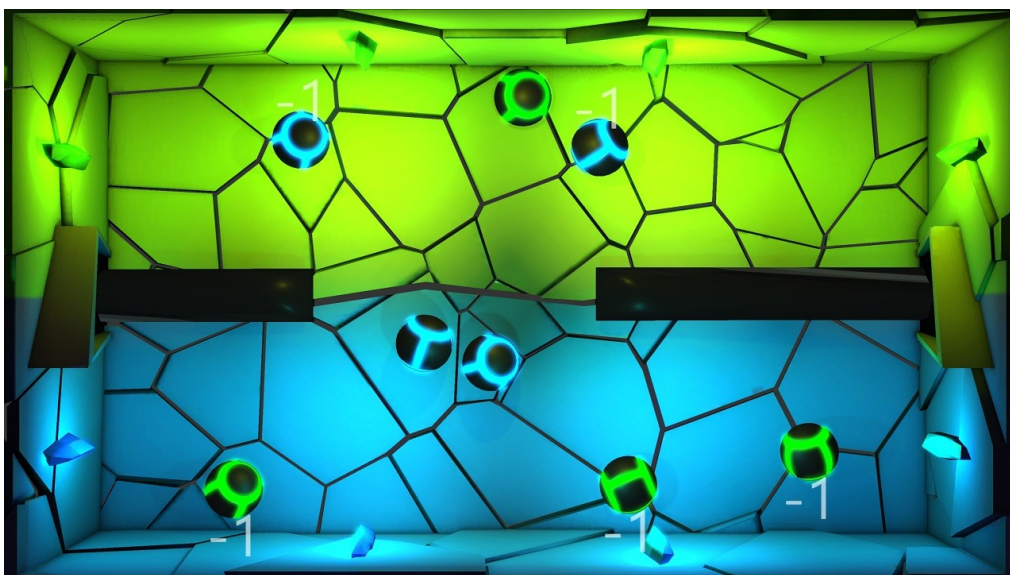


DIVIDED ATTENTION SORTER

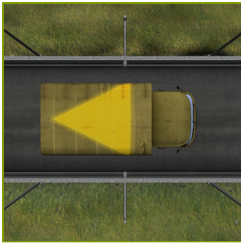
SAMPLE SETTINGS



Difficulty 1/3	
Duration 30s	Range 20% 80%
Number of objects 4	Gap size 150%
Speed of objects 100%	



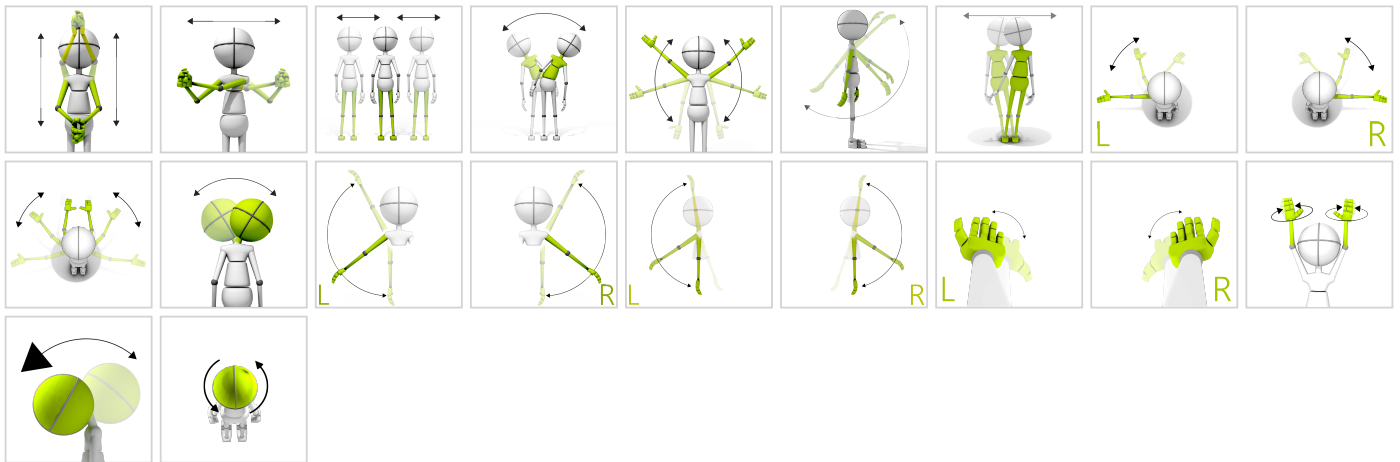
Difficulty 1/3	
Duration 30s	Range 20% 80%
Number of objects 4	Gap size 150%
Speed of objects 100%	



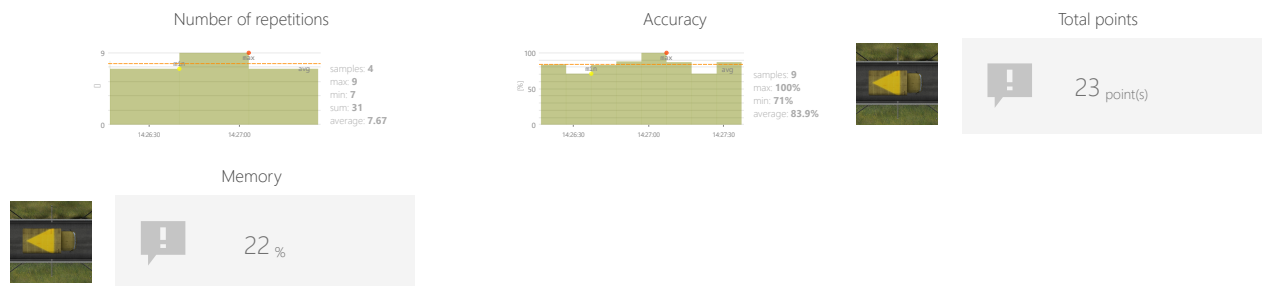
MEMORY TRUCKS

Measure and train individual's skills to memorize information.

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Range
- Variations

OBJECTIVES

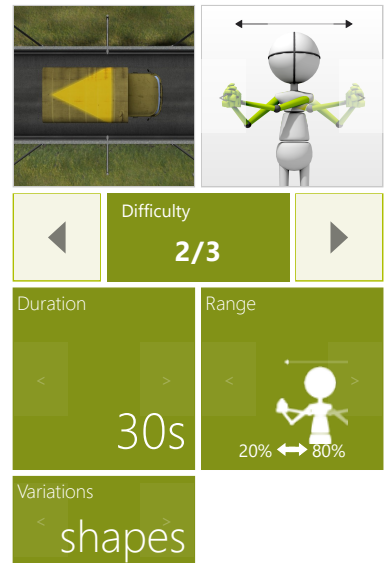
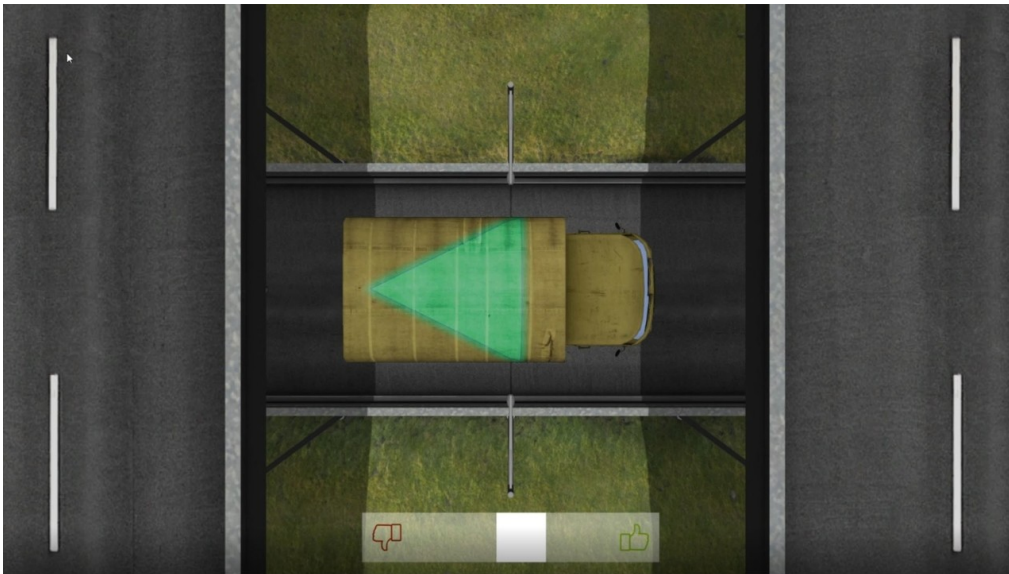
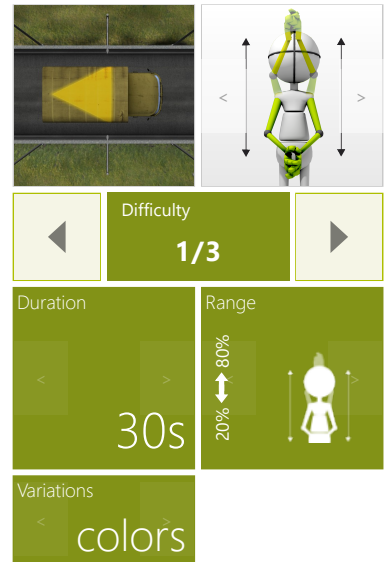
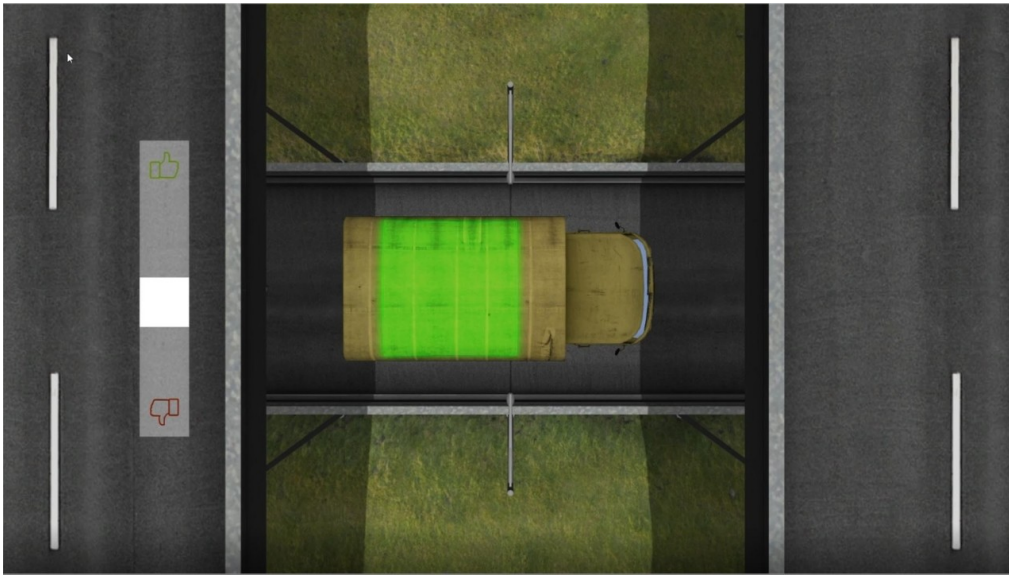
- Logical tasks
- Focusing
- Perceptivity

INSTRUCTION FOR PATIENT

Remember the shape and/or its color on the roof of the car you see. Decide with thumbs up or down whether the next car has the same shape and/or color on the roof as the previous one.



SAMPLE SETTINGS



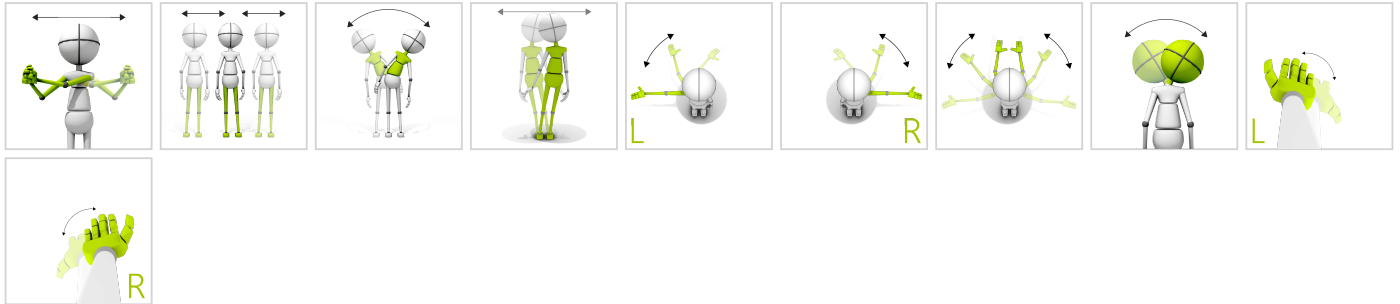


PROBLEM SOLVING

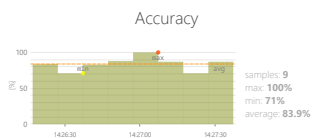
CLONES

Measure and train individual's skills to reach a solution of specific problems. Problem solving may include mathematical or systematic operations and can be a gauge of an individual's critical thinking skills.

CONTROL MODES



RESULTS



Total points

19 point(s)



Problem solving

34 %

ADJUSTMENTS

- Task duration
- Time to complete action
- Range
- Number of pairs

OBJECTIVES

- Perceptivity
- Visual motor coordination
- Logical tasks

INSTRUCTION FOR PATIENT

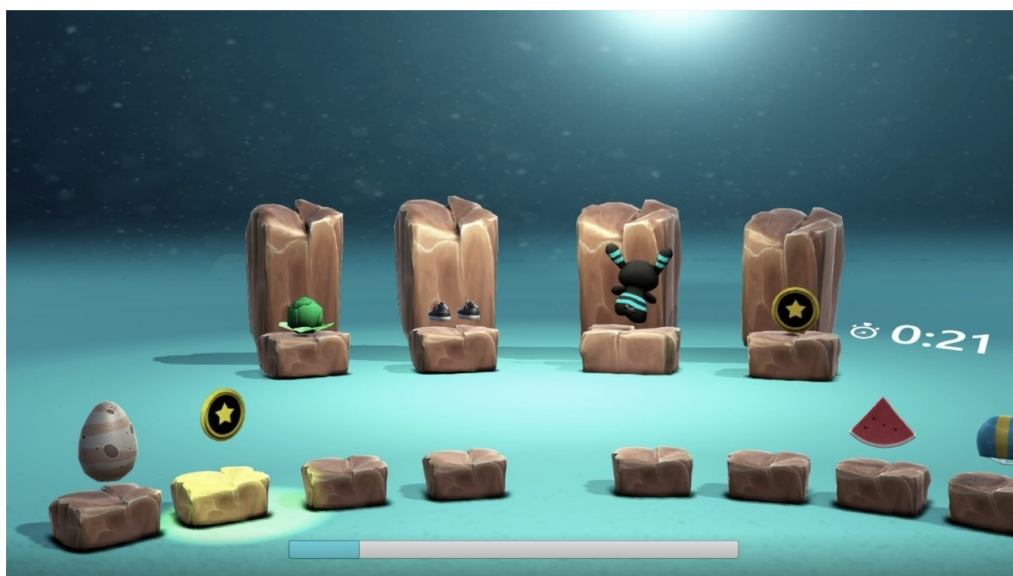
Select the item which has a pair on the screen.





PROBLEM SOLVING

CLONES

SAMPLE SETTINGS





◀	Difficulty 1/3	▶
Duration 90s		Minitask duration 30s
Range 20% ↔ 80%		Number of pairs 4

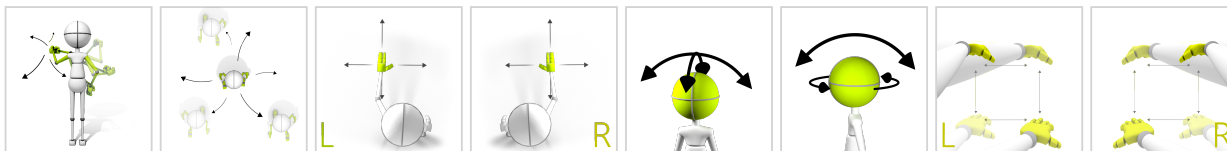


PROBLEM SOLVING

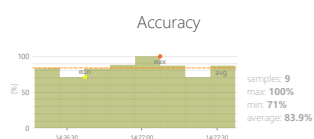
MAZE

Measure and train individual's skills to reach a solution of specific problems. Problem solving may include mathematical or systematic operations and can be a gauge of an individual's critical thinking skills.

CONTROL MODES



RESULTS



Total points



16 point(s)



Problem solving



31 %

ADJUSTMENTS

- Task duration
- Range
- Show path
- Maze size

OBJECTIVES

- Logical tasks
- Planned movements
- Planning and Strategy

INSTRUCTION FOR PATIENT

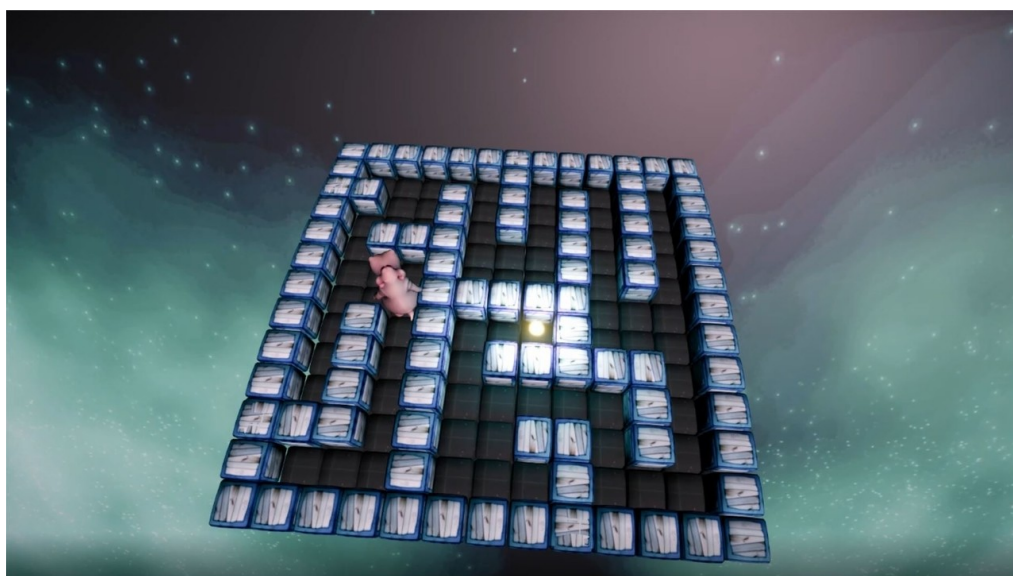
Lead the hippo through the maze to the glowing target.





PROBLEM SOLVING

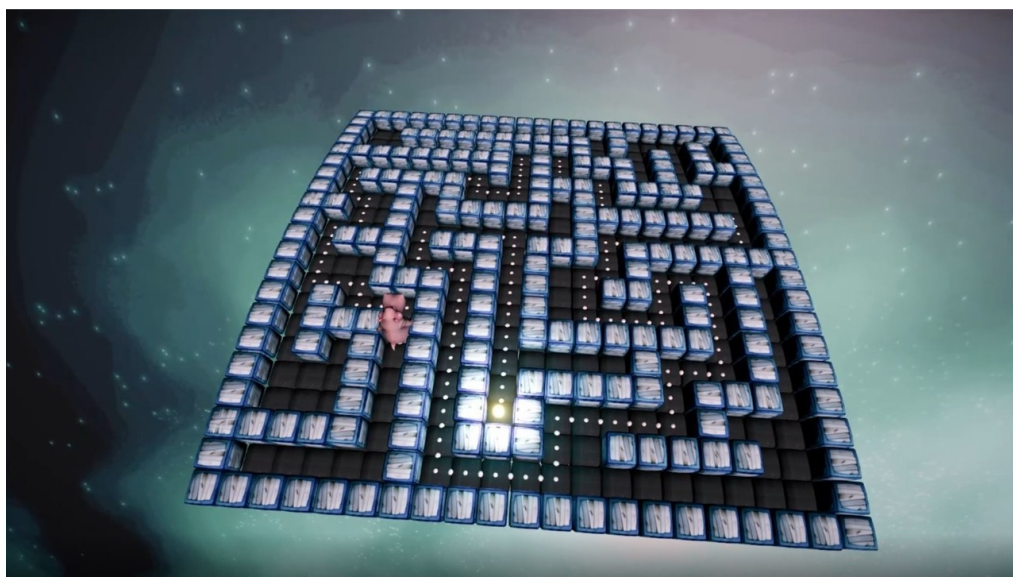
MAZE



SAMPLE SETTINGS





◀	Difficulty 2/4	▶
Duration 90s		Range 20% 80% 20% 80%
Show path No		Maze size 6





◀	Difficulty custom	▶
Duration 90s		Range 20% 80% 20% 80%
Show path Yes		Maze size 10

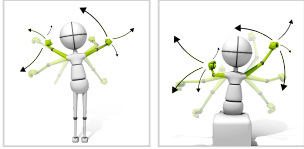


PROBLEM SOLVING

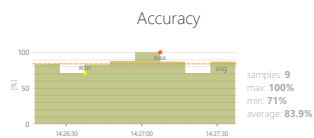
KITCHEN DISH SORTER

Measure and train individual's skills to reach a solution of specific problems. Problem solving may include mathematical or systematic operations and can be a gauge of an individual's critical thinking skills.

CONTROL MODES



RESULTS



Total points

28 point(s)



Problem solving

29 %

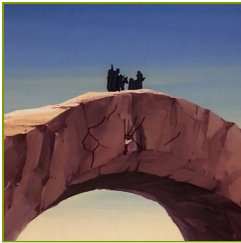
ADJUSTMENTS

- Positions to have targets on
- Task duration
- Show hints

OBJECTIVES

INSTRUCTION FOR PATIENT

Put all the dishes in the kitchen cabinets. To open drawers and cabinets, you need to pull their handles. Be careful not to drop the dishes on the floor, or they will break! If you are using touch controllers, pressing the grip button under your middle finger will activate the controller.

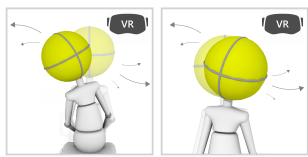


PHOBIAS AND FEARS

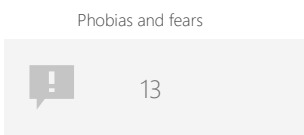
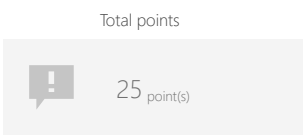
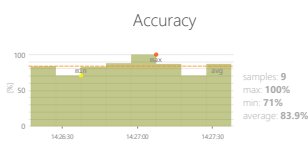
CANYON

toAdd(catDesc550)

CONTROL MODES



RESULTS



ADJUSTMENTS

- Task duration
- Object size width

OBJECTIVES

INSTRUCTION FOR PATIENT

Collect as many flowers as you can. Look straight onto it to collect one.